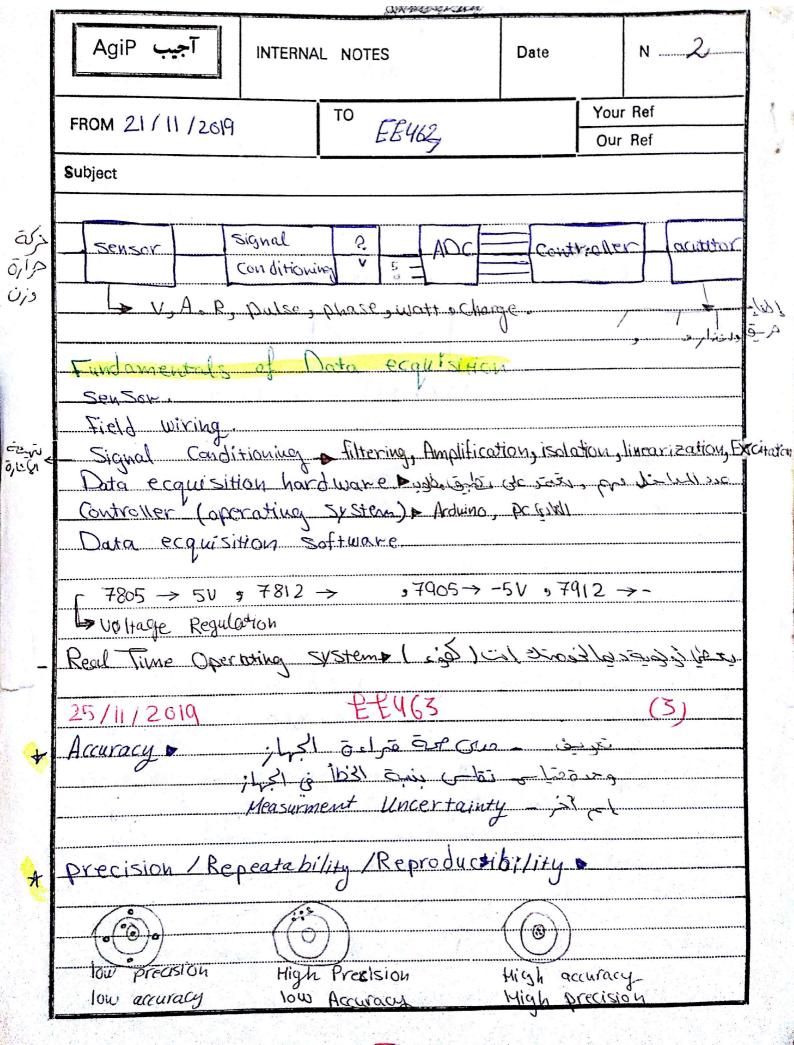
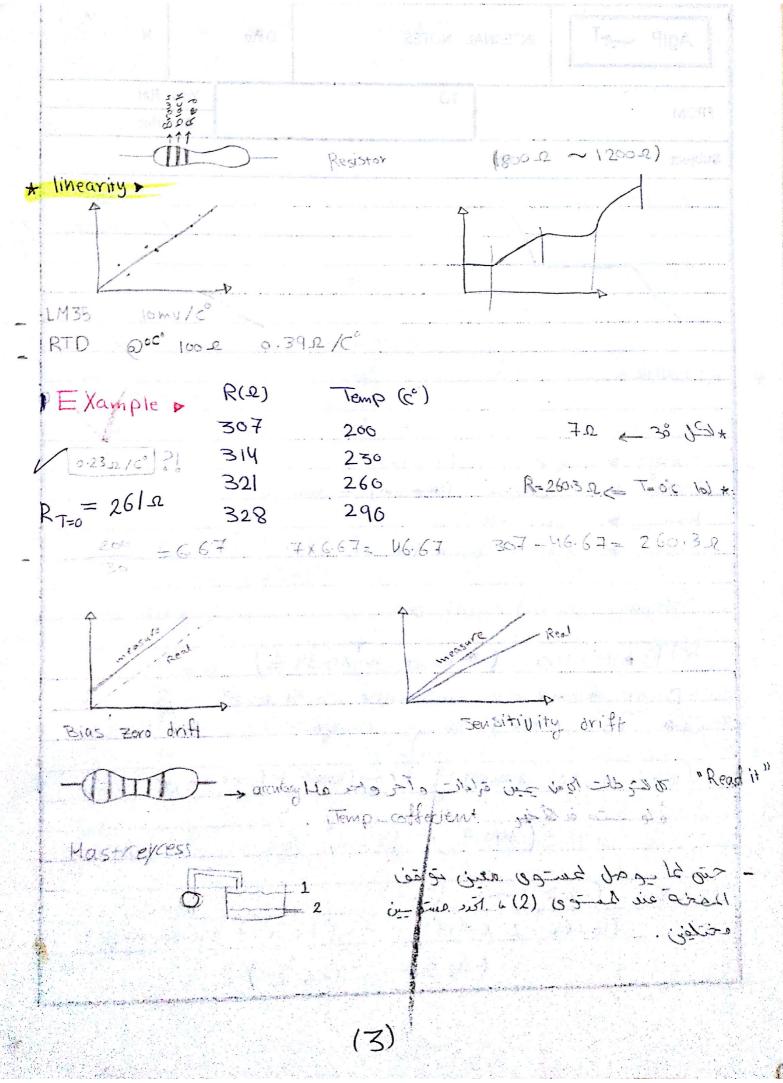
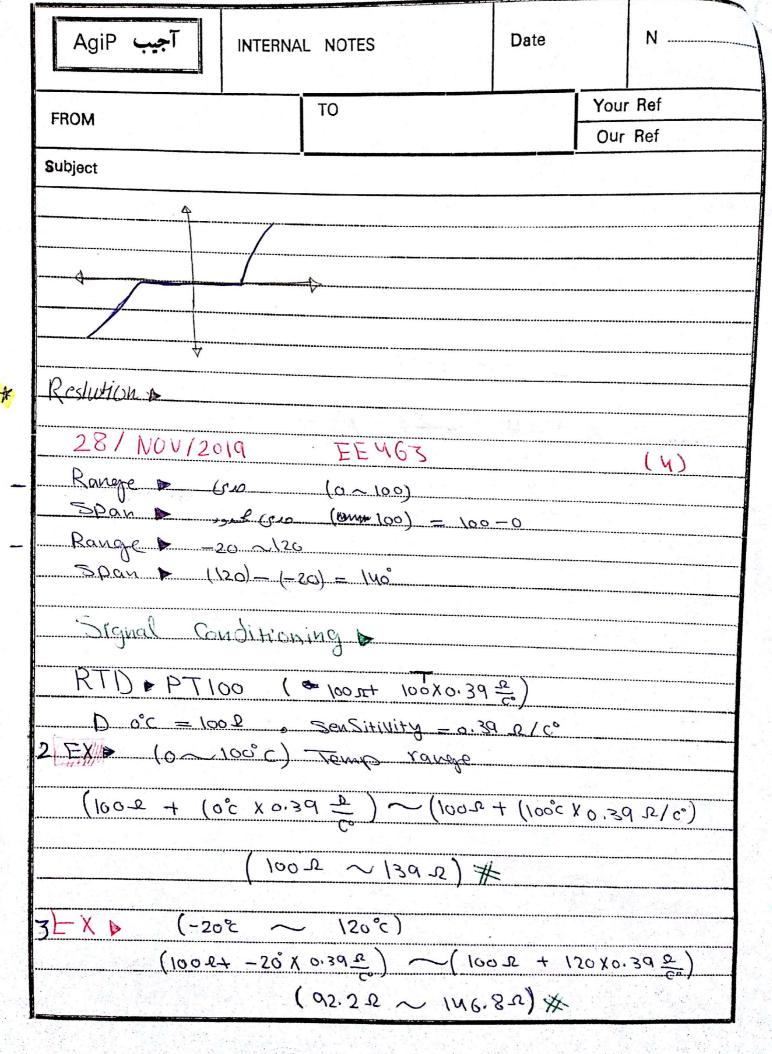
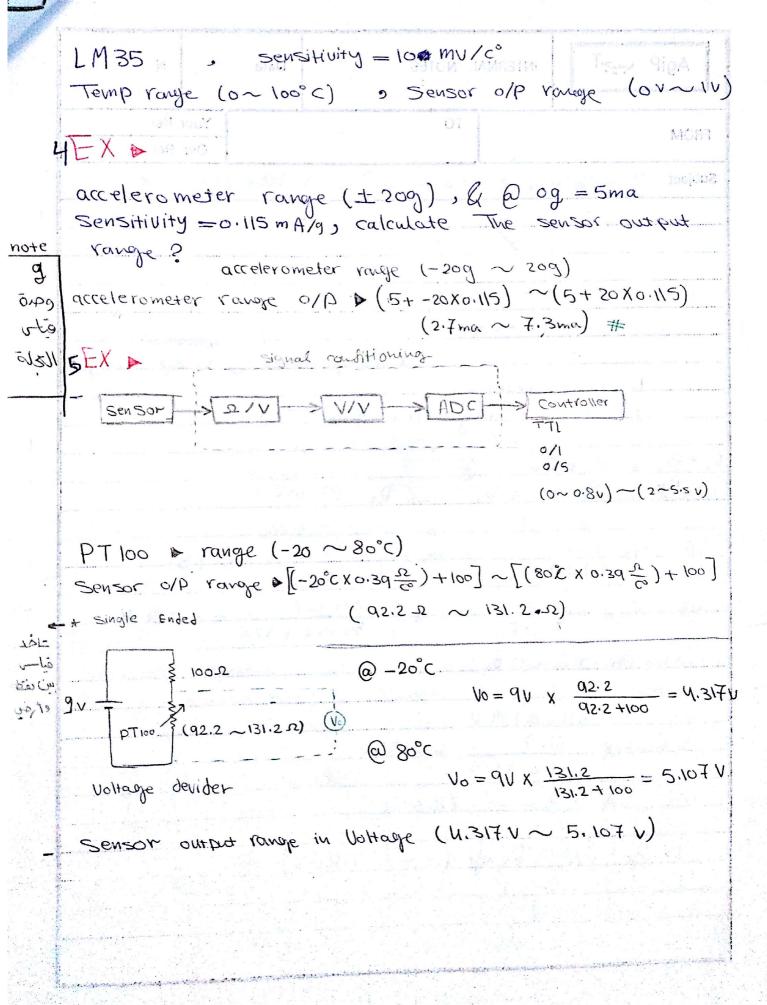
zeyad hamza @ cet.edu.ly Data acquisition 18/11/2010 (1) EE 463 to Transfer information from Tranducer to Controller by changing The electrical signal to Digital 1- RTD > PT 100 -> Transducer for Temp can read [0~139 2]  $0 \text{ oc} = 100 \Omega, \quad [0.39 \Omega/C^{\circ}]$ => 100 + (23 x0.39) = 108.97 D CMOS Day and Look a self was I 0 on off on off (3~18) Welt 5 Volt (2 ~5.5)v ( 4.9 )V \* The is I am spine ) be ( time alies to it is it 137 D what's The temp. 2 FE = 2001 - 2 FEI \* T= 372 / 0.39 T = 94.87C Data ecquisition: is The process by which physical phenomena from The Red world are Transformed into electrical signals That are measured & converted into digital format for processing analysis & Storage by a Computer. > Tranducer for measure Temp. 2- $(o \sim loo^{\circ}c)$   $lo m V / c^{\circ}$ .. [o~ 1·v]

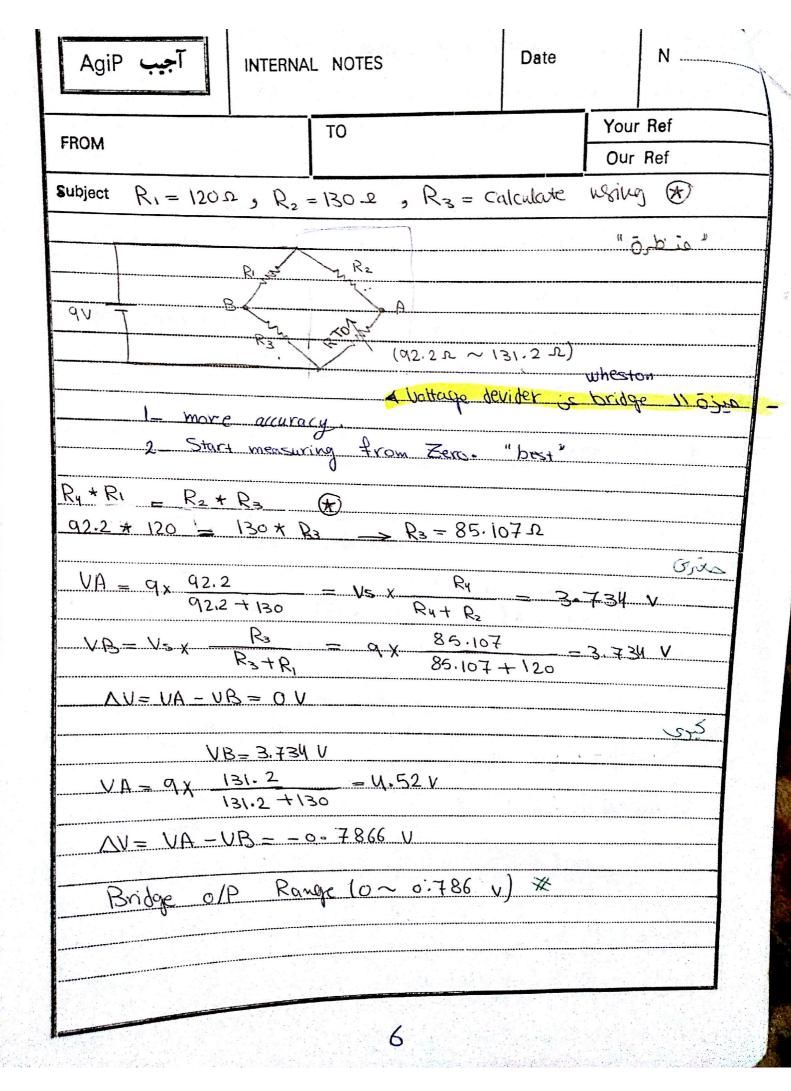


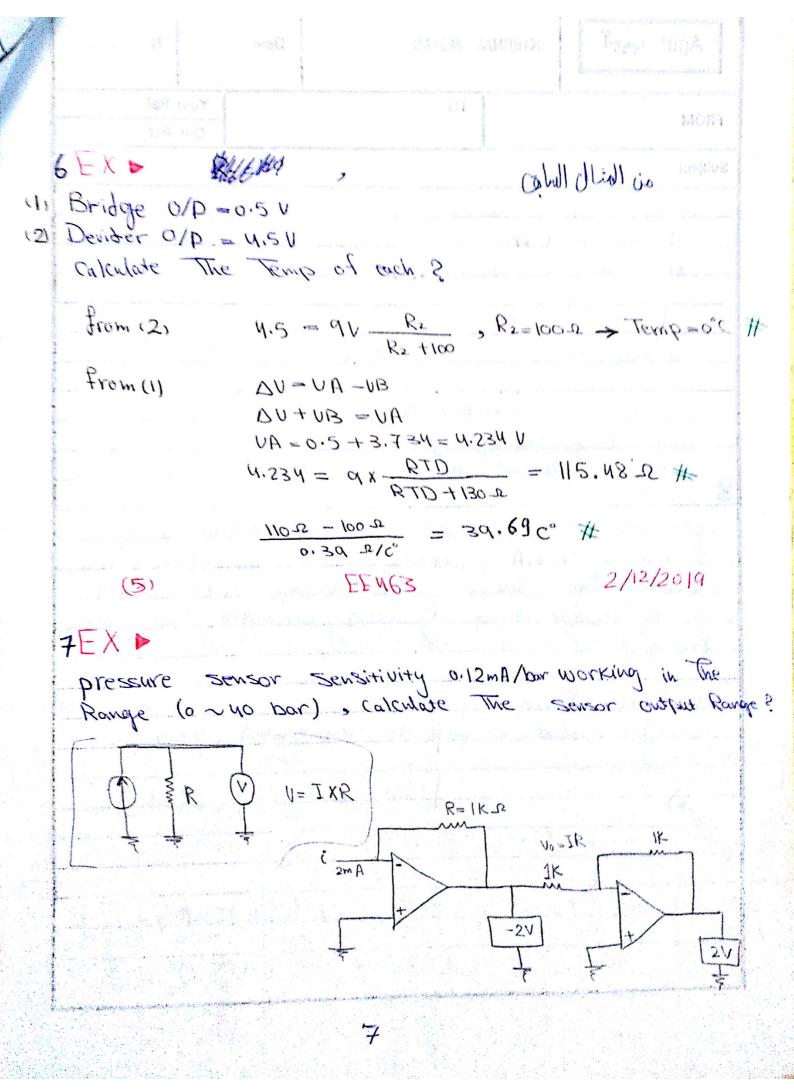


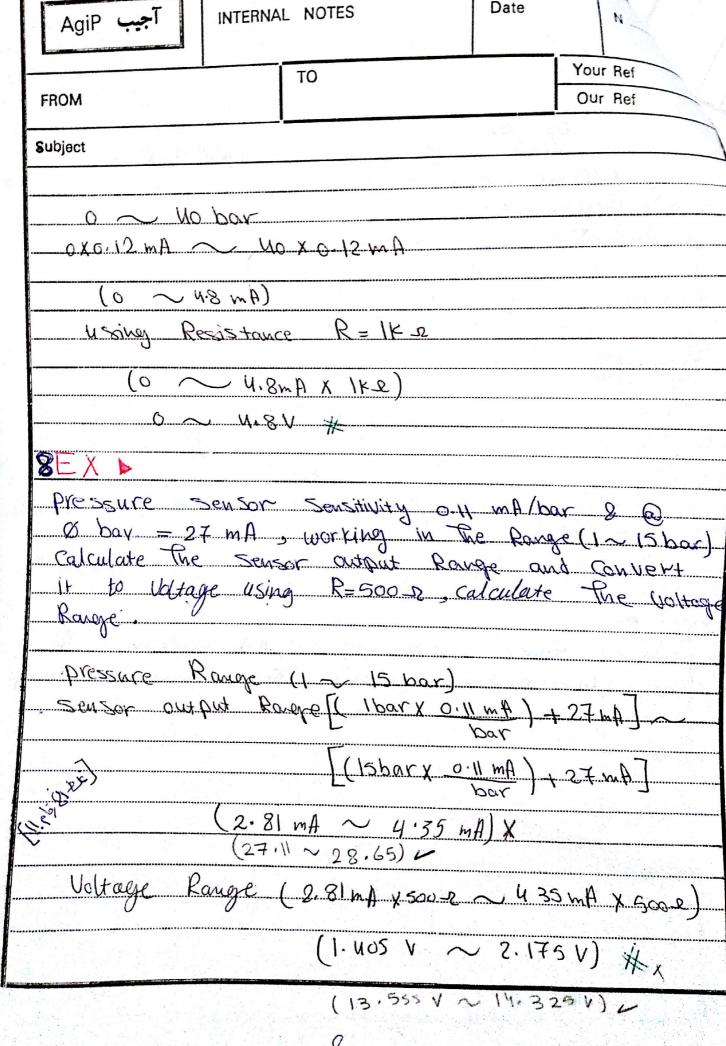
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8

9 X X >

LM35: Temp sensor working in the Range (0~100°C) with sensitivity 10mu/c°, calculate the output sensor in the Range (25~40°C)

accelerometer MSloo2 MSloo2 [MSlob] unit full scale acceleration 
$$\pm 2$$
  $\pm 5$   $\pm 10$   $g$  scale factor southwelly 1350 540 [270] mv/g

$$V[t] = V[t-1] + ([A[t] + A[t-1]) * T$$

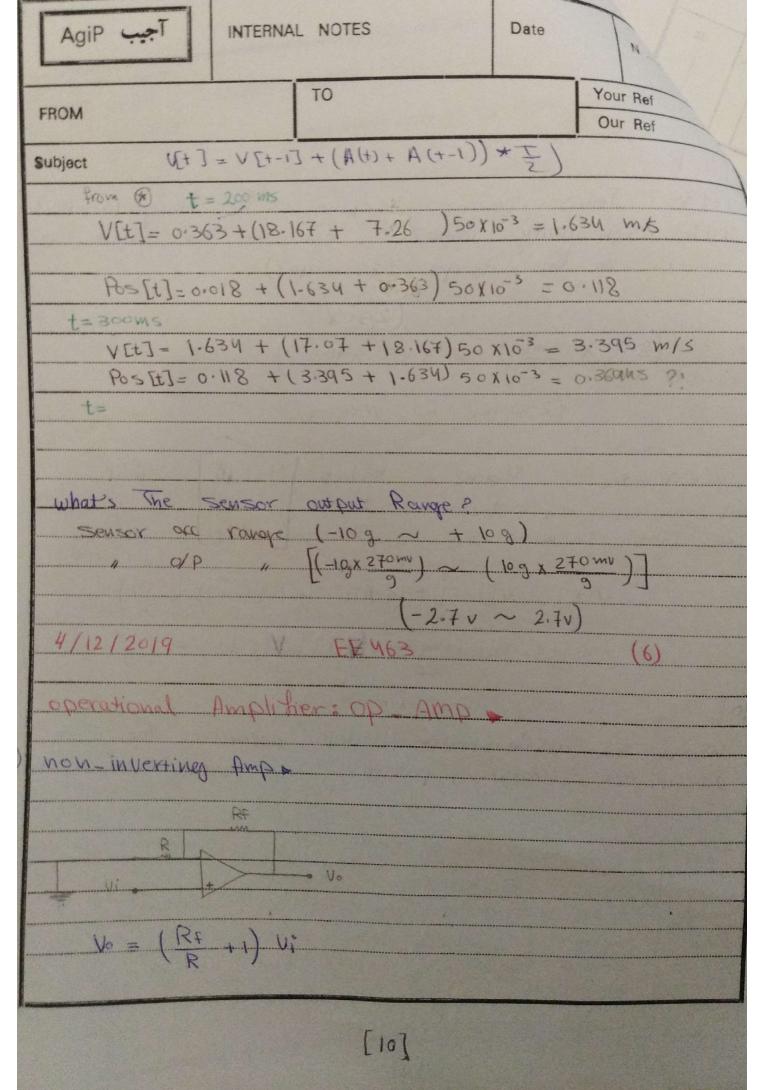
$$Pos[t] = Pos[t-1] + ([M[t] + K[t-1]) * T$$

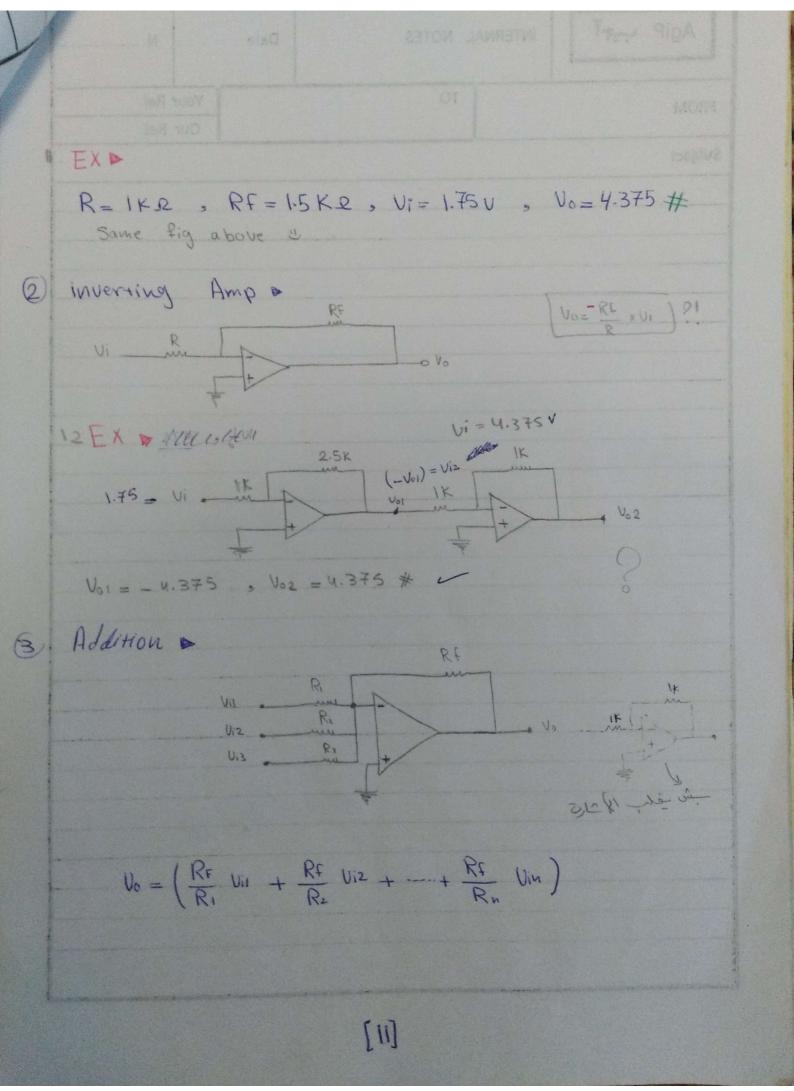
DEX

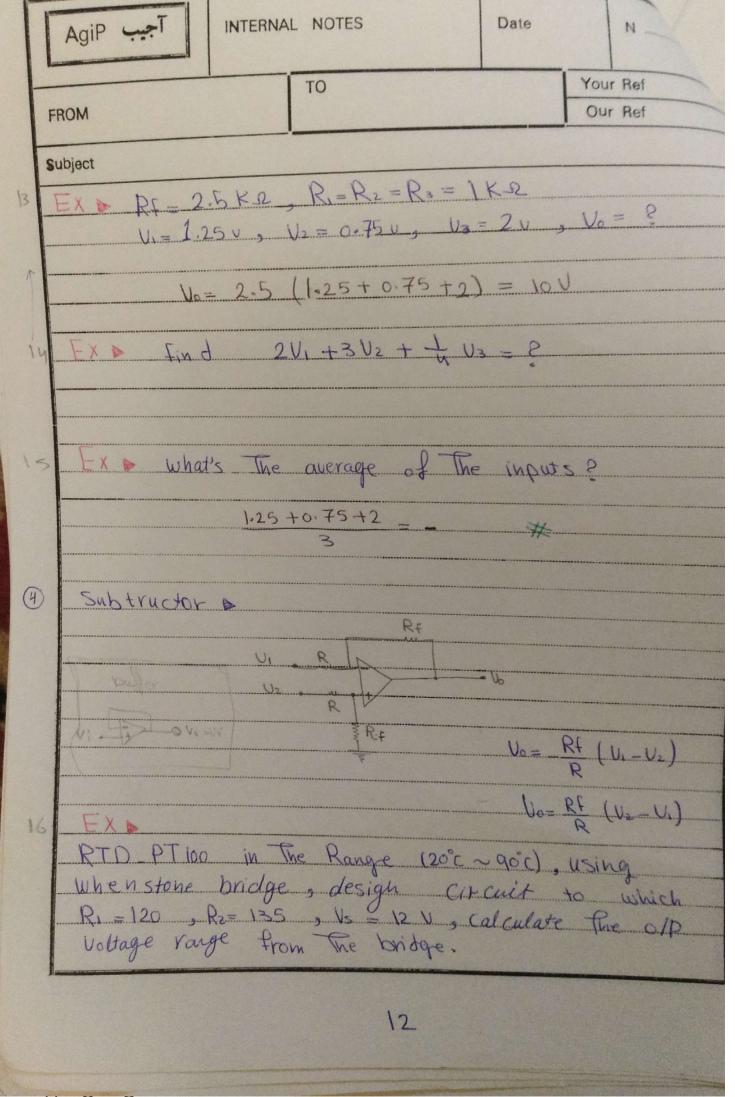
Using the accelerometer MS1010, calculate the acceleration, velocity, position, for each following Reading

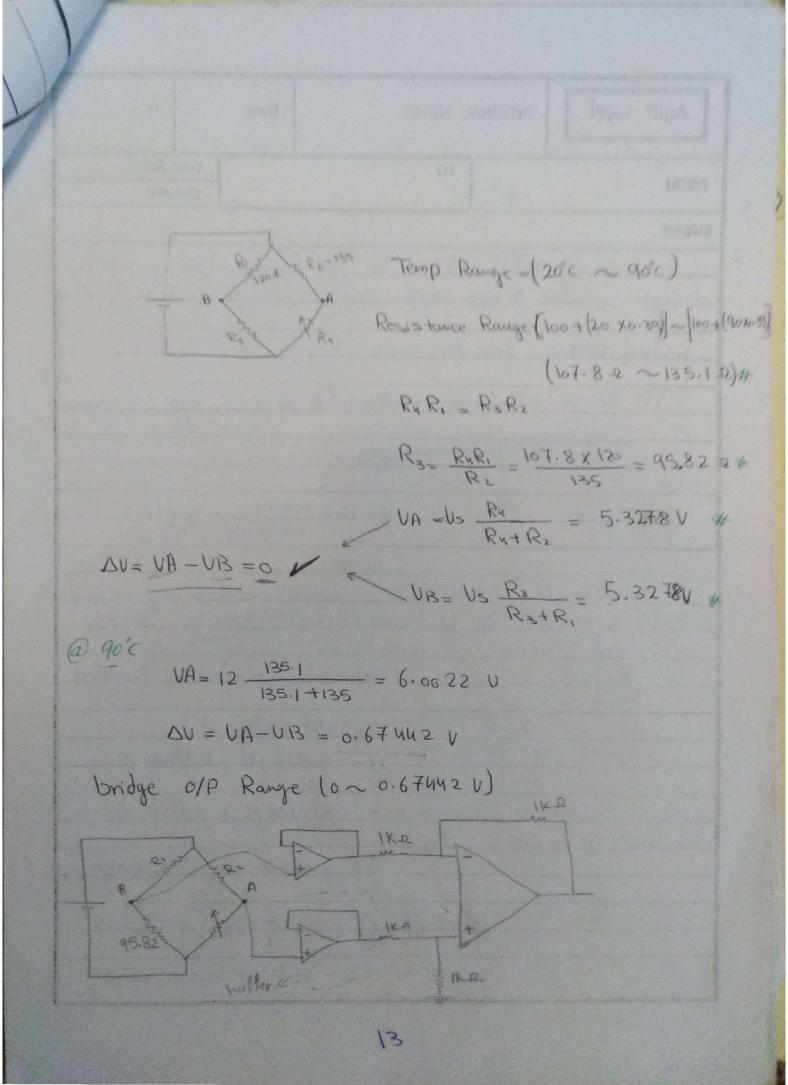
interval = 100 ms A[t] velocity

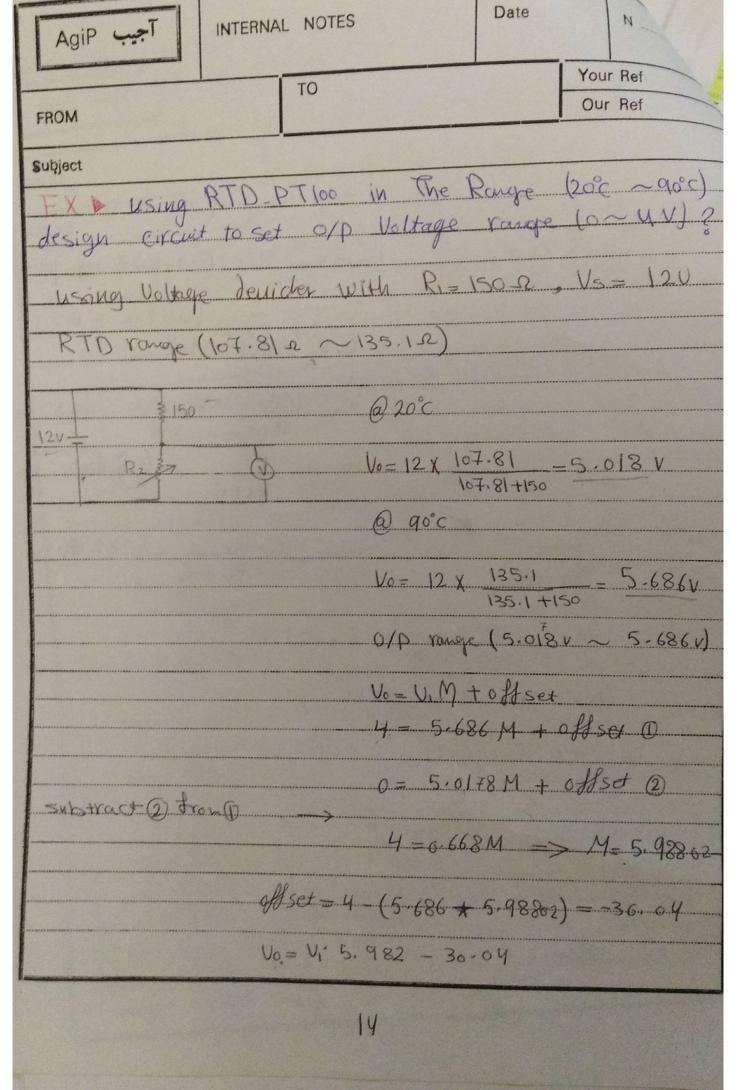
	Time	acc oudput (mv)	accelatation (9)	(m/s2)	V[t] WS	Displacement	Position (m
to	0	0	0	O	0	0	0 :
t!	100 ms	200 MU	200/270=0.749	0.74xq.81=7.26	0.363	m810.3	0.018 m
t2	200 Ms	500 my	500/270=1-85 %	18.167	1.634	C.118 M	0-118m
t <sub>3</sub>	300 ms	470 mv	470/270= 1-749	17.07	3.395	0.218 m	0.218 m
t	400 m s	200 mU	= 0			The second secon	
		owy.	0.3	0			-
		-120 WV	-0.444	-4.36			

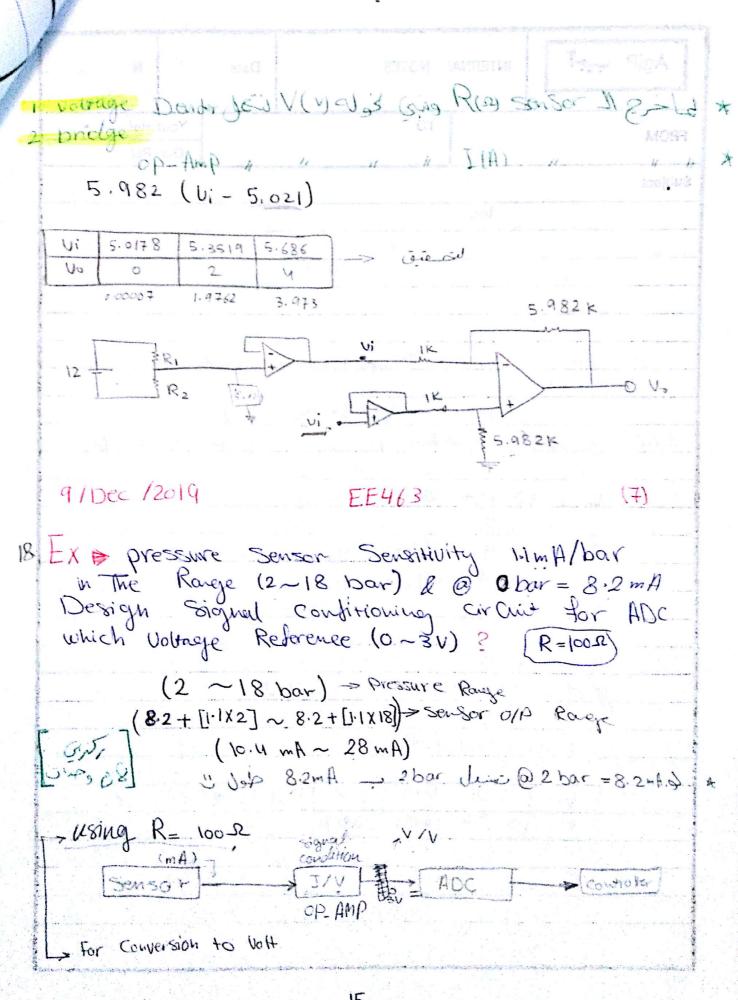


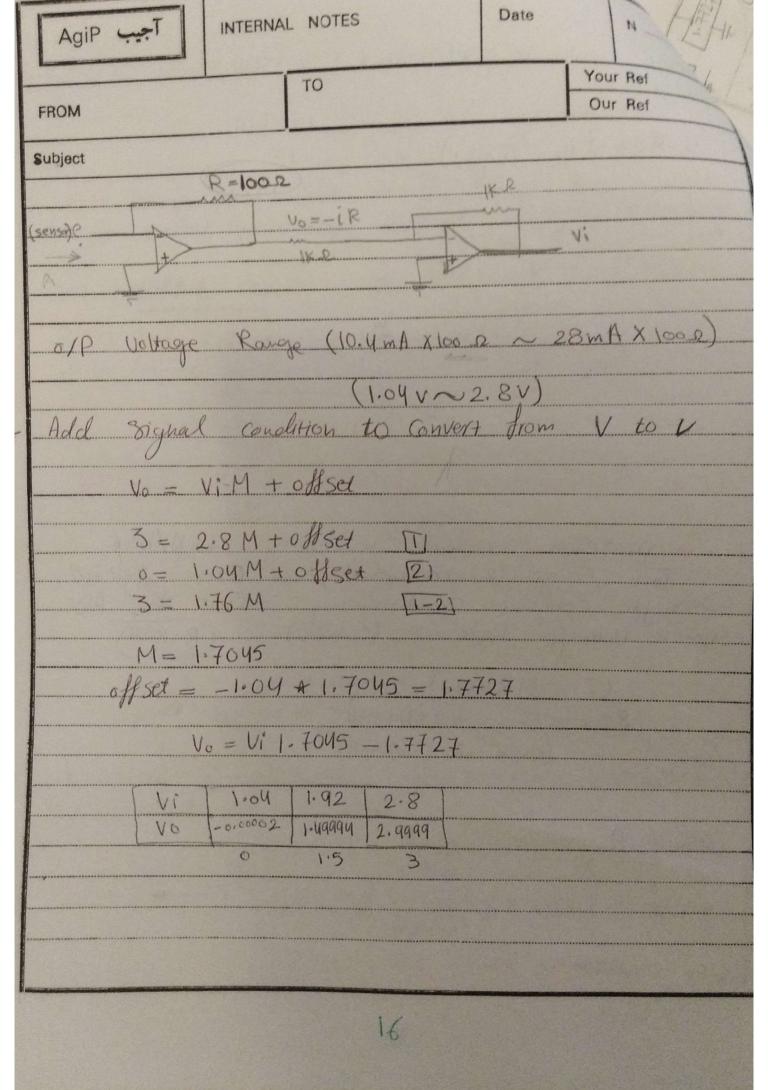


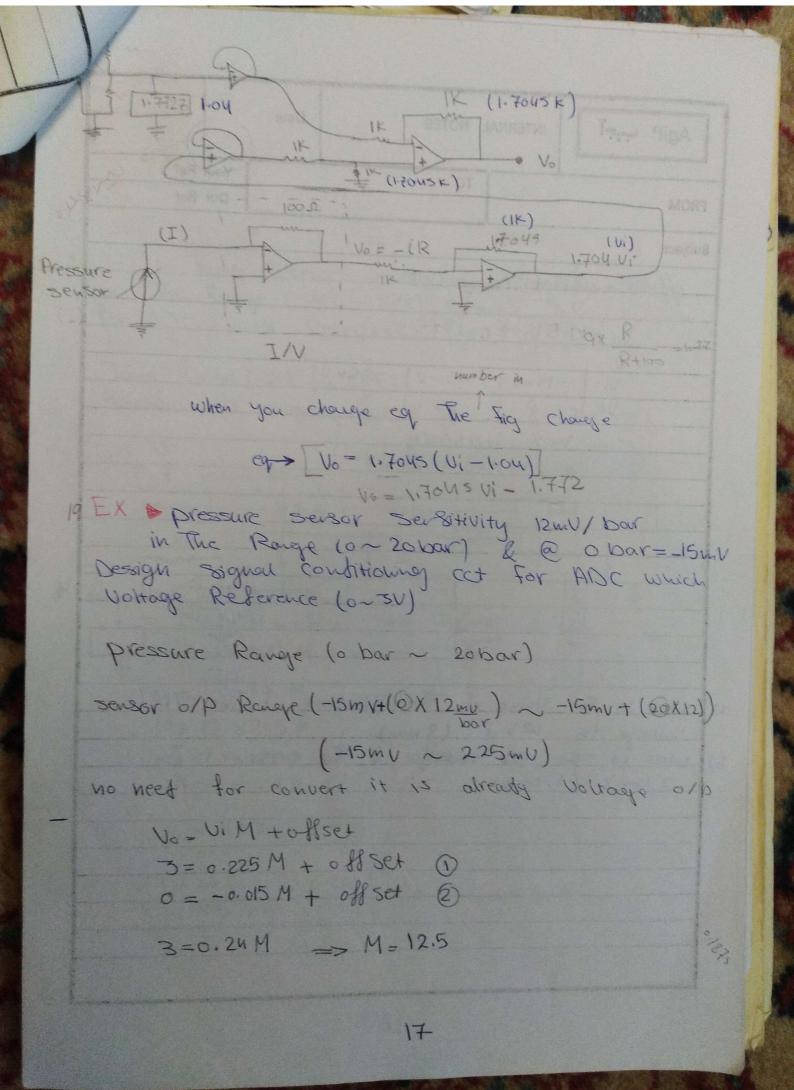


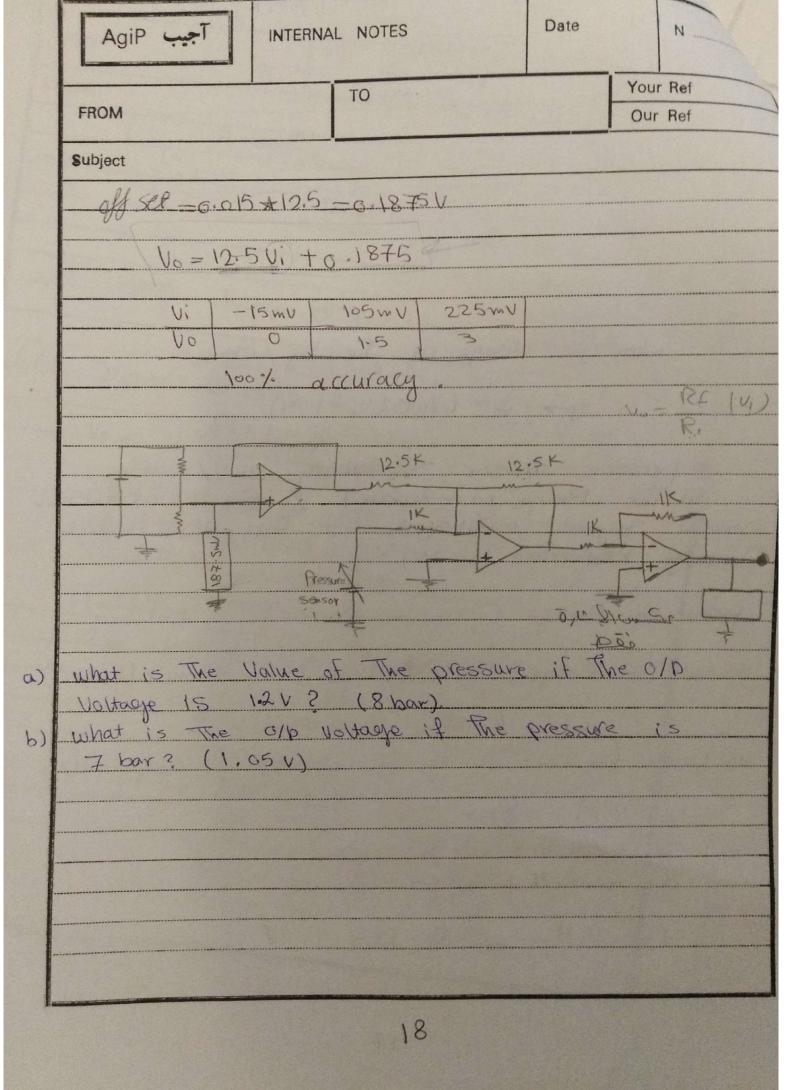


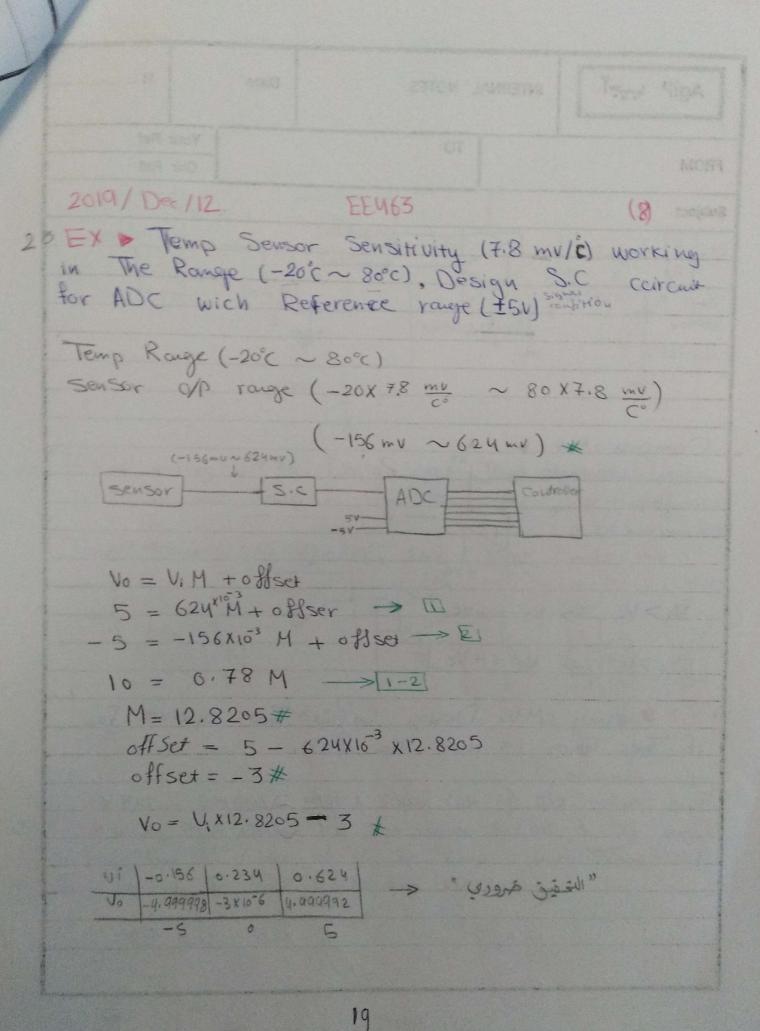


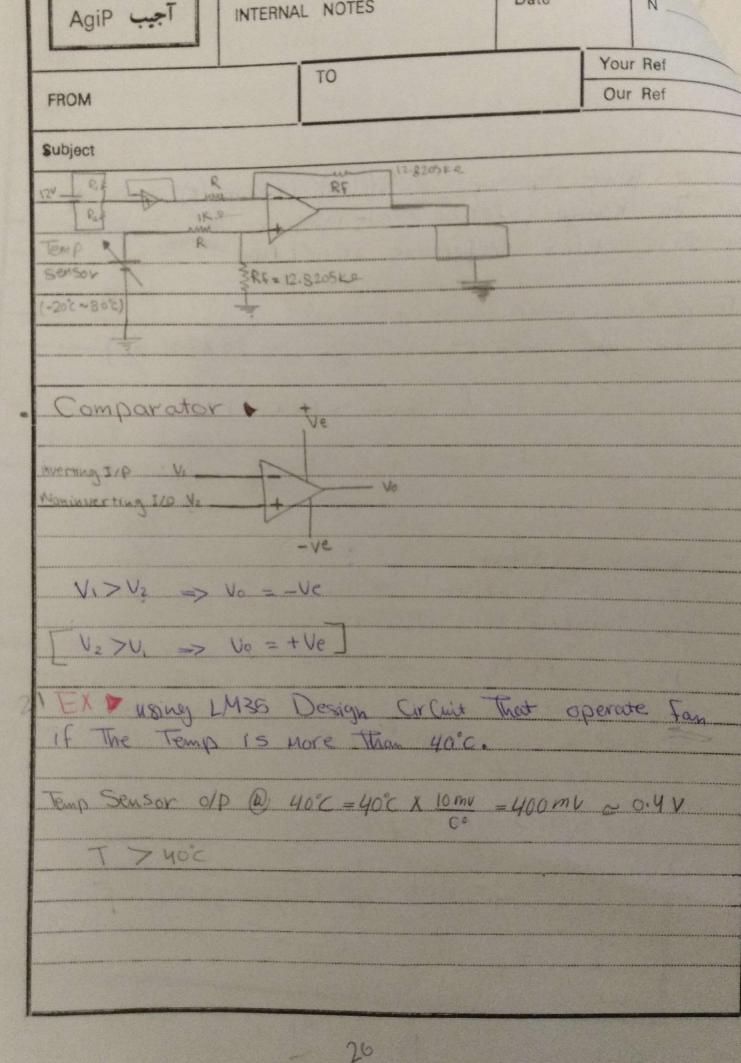






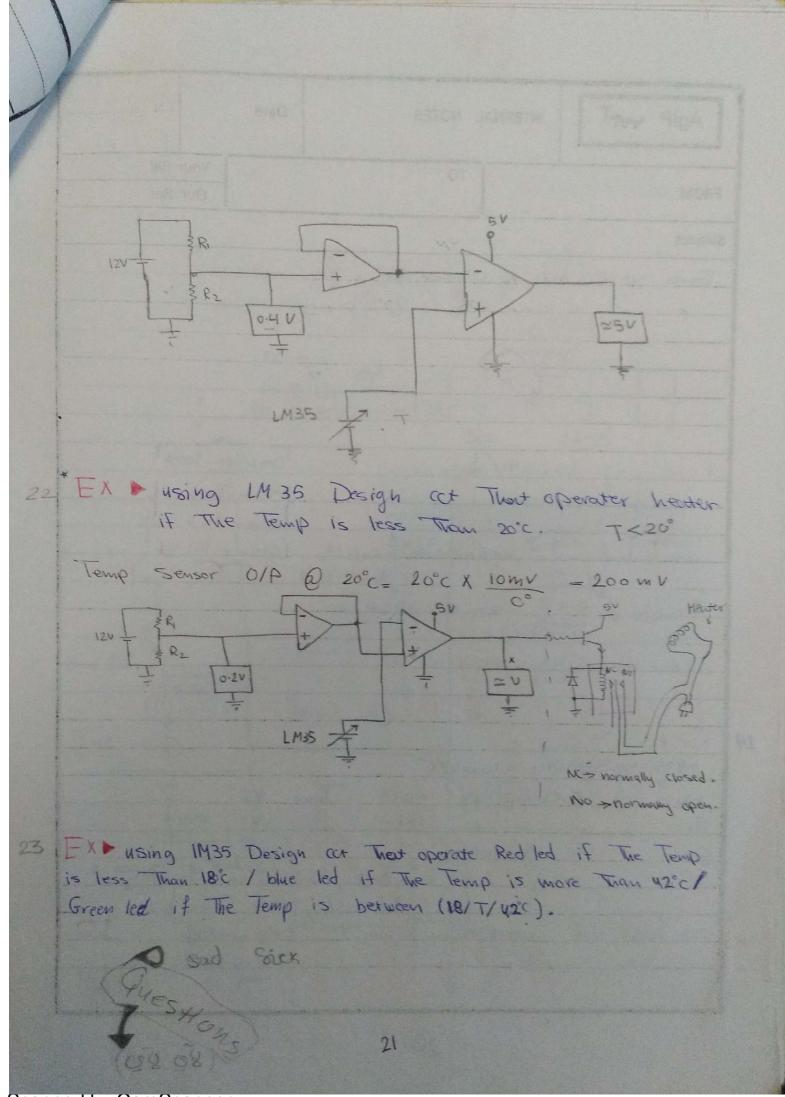


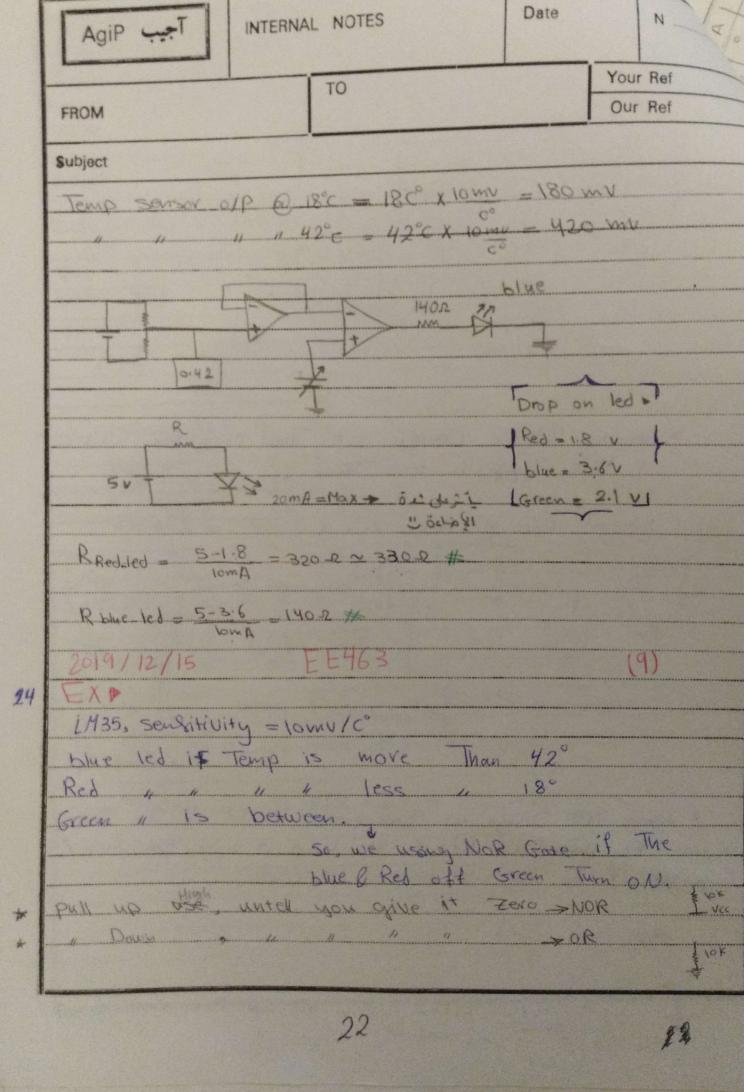


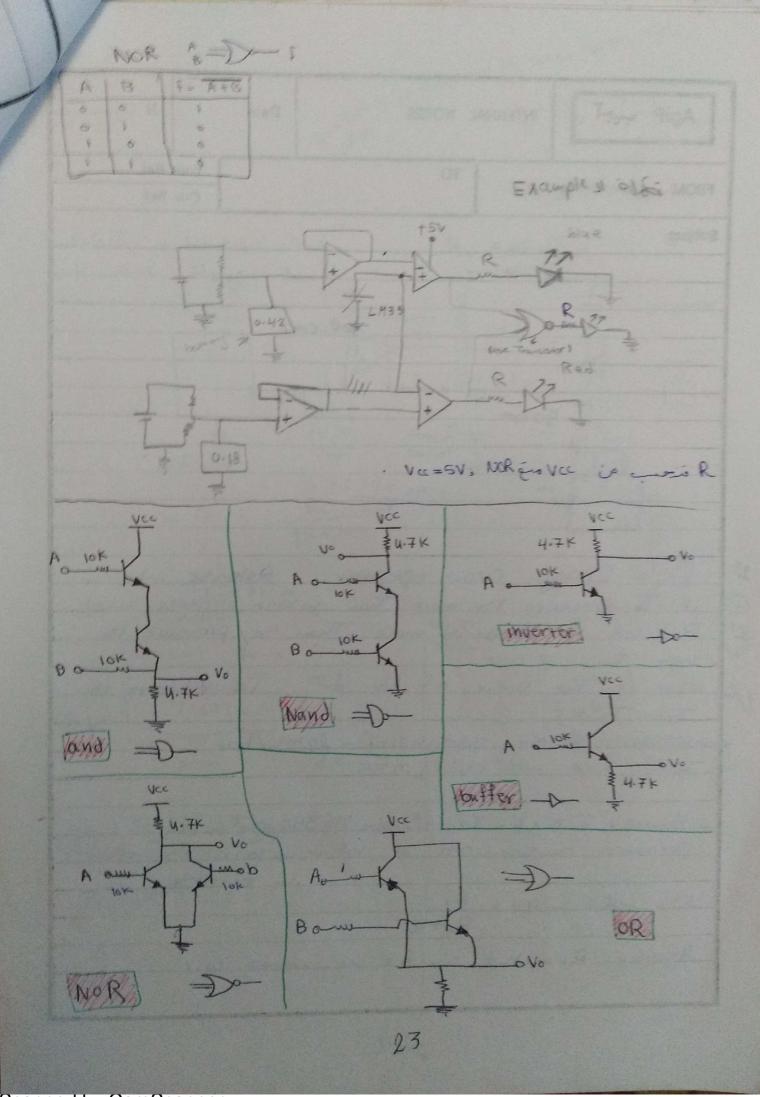


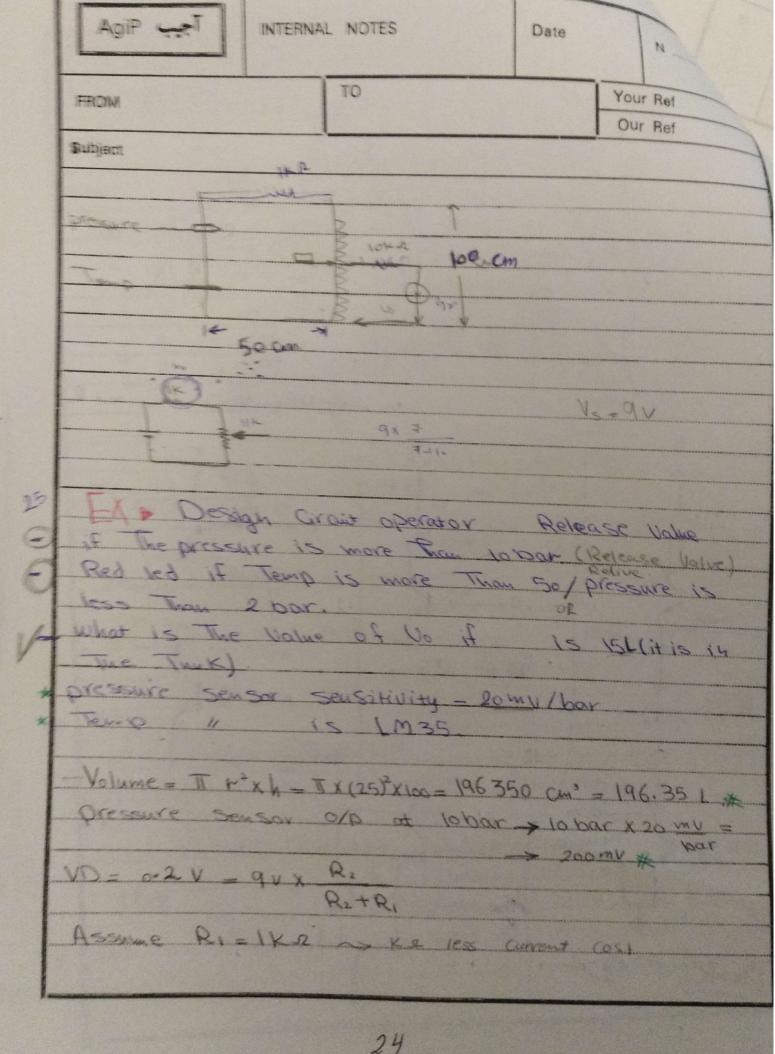
1)

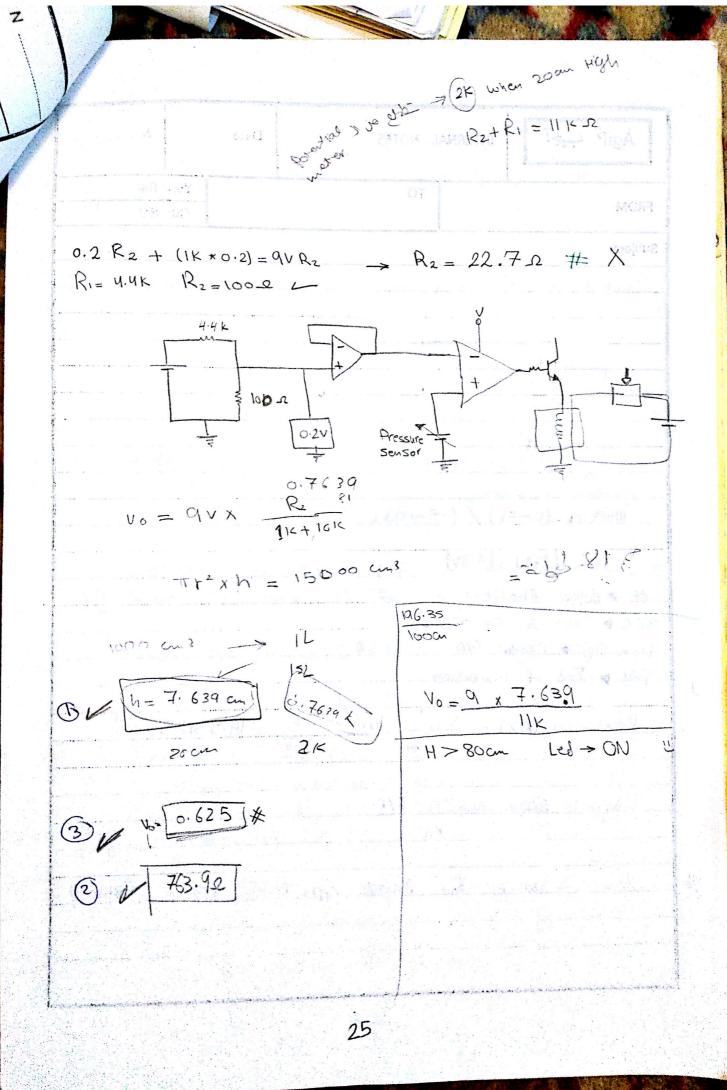
)

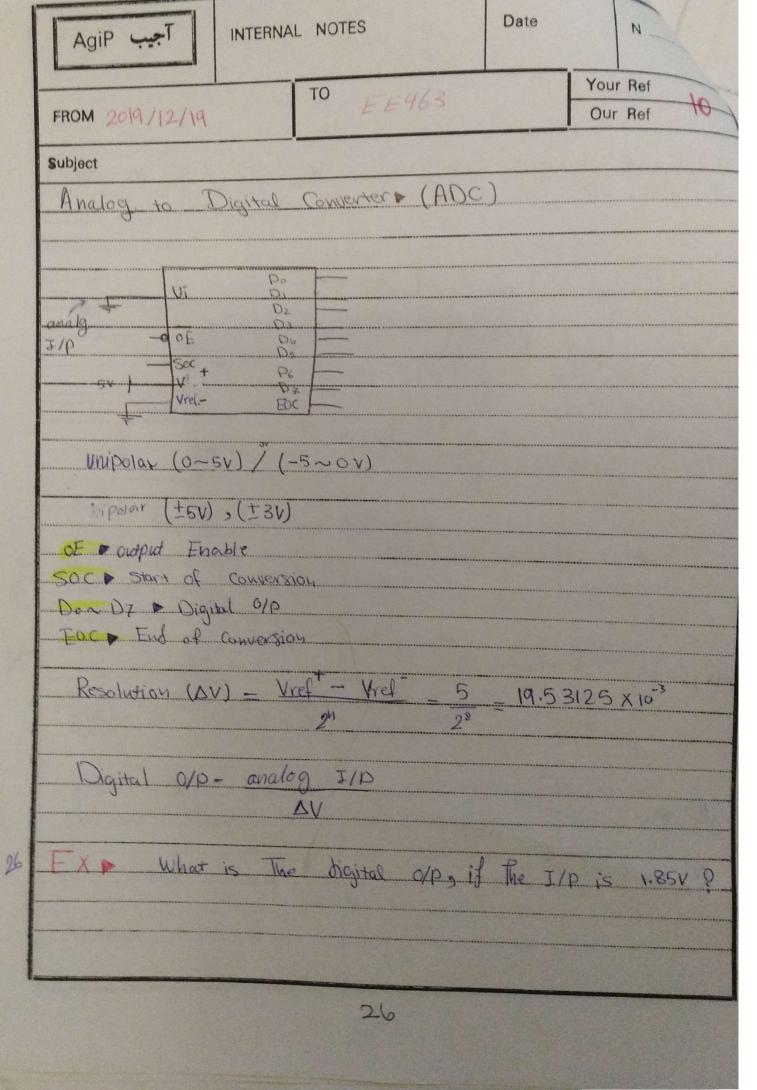




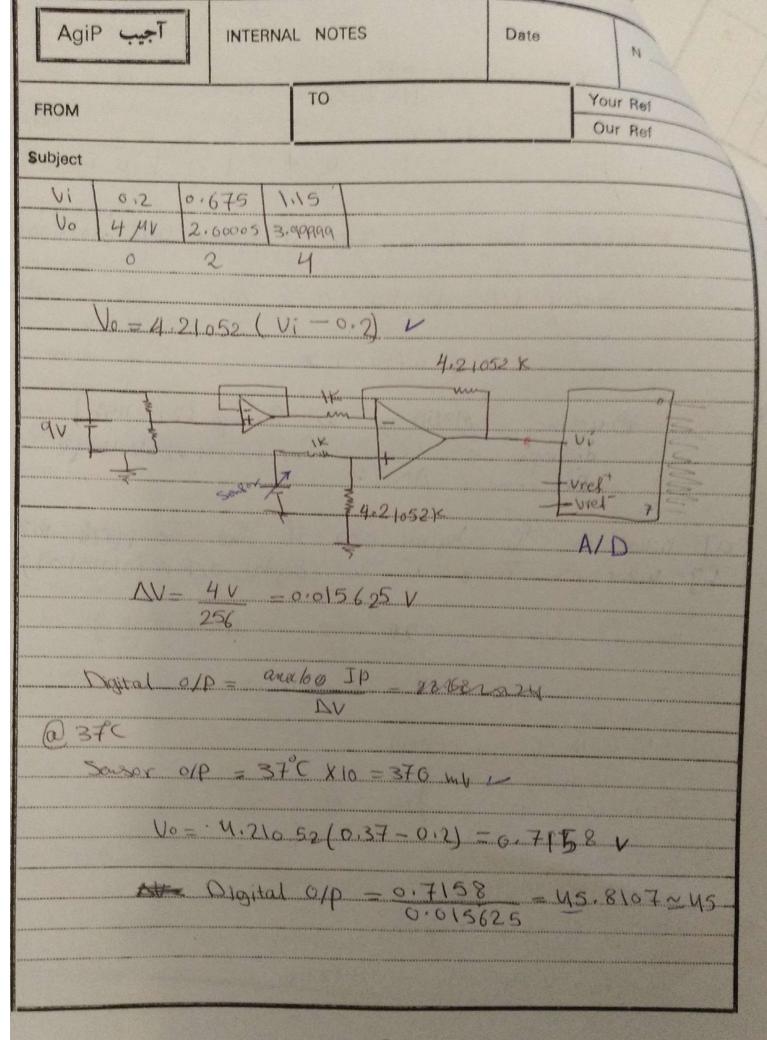




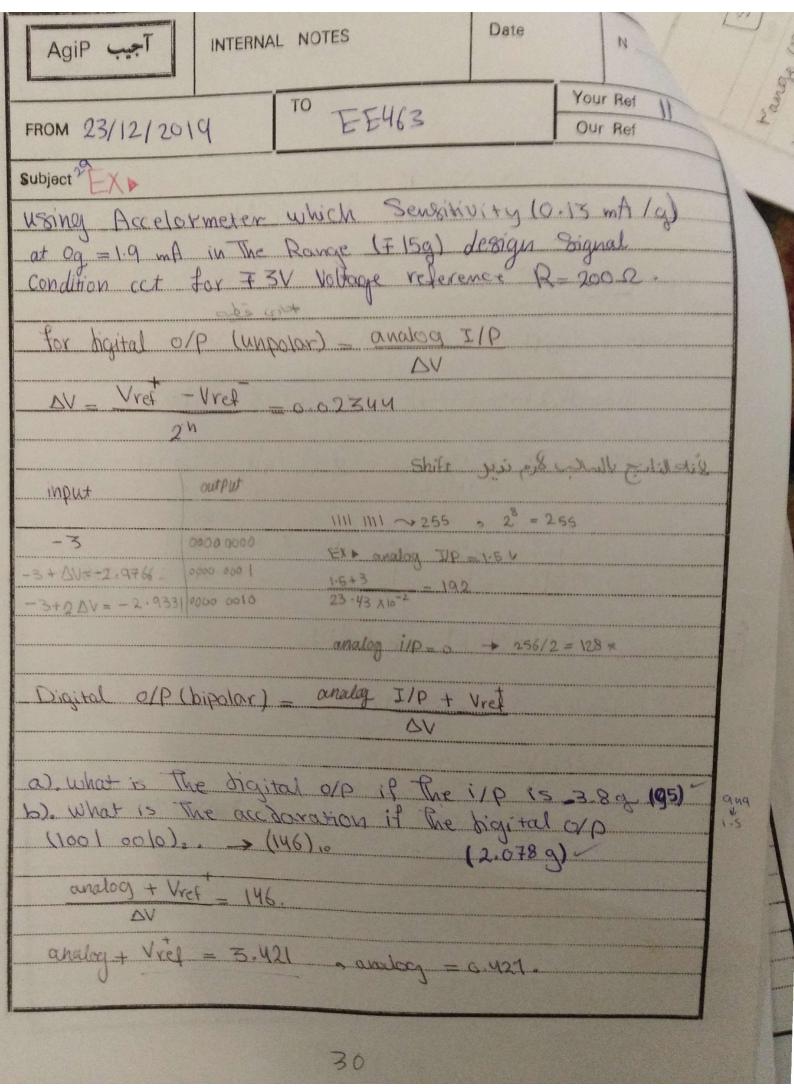


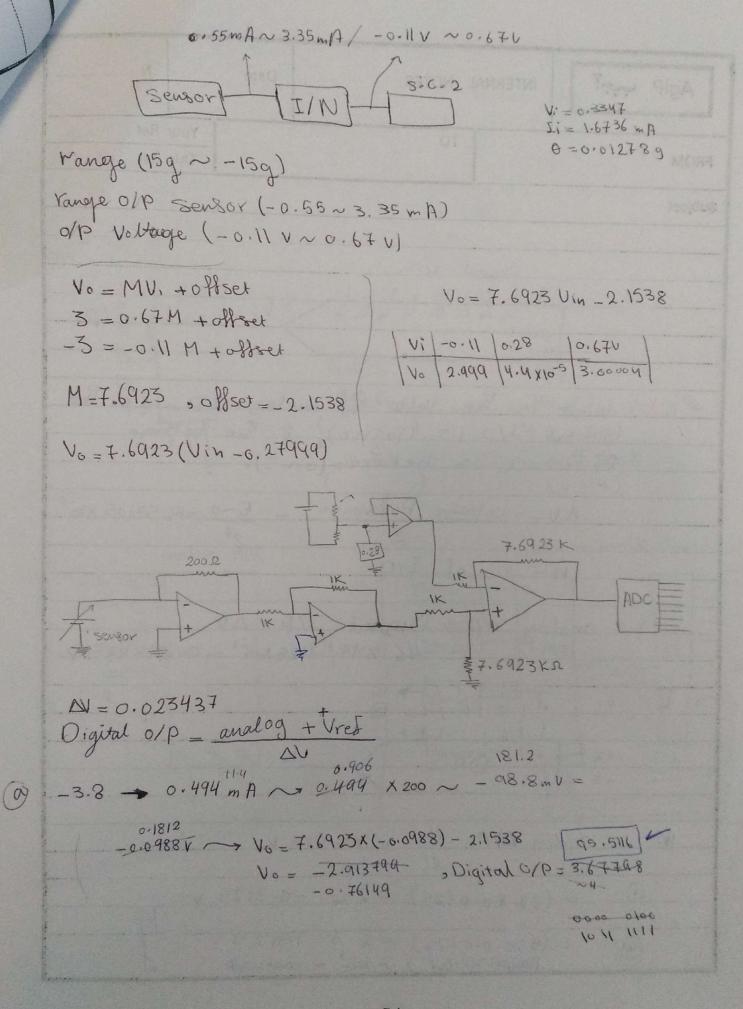


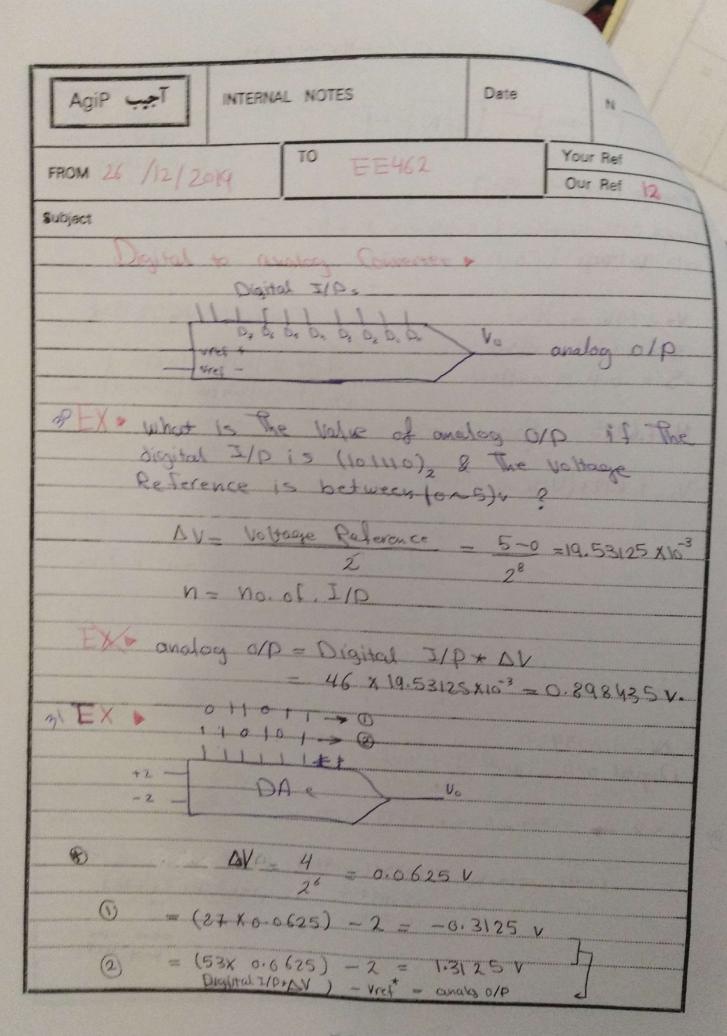
Digital 0/D= 1.85 19.53125×10-3 = 94.72 ~ 95 128 64 32 16 8 4 2 1 0 1 0 1 1 1 1 0 128 GA 3516845 27 = X > what's The analog I/P, if Digital O/P 01011000 analog J/P = Digital O/P X DV = 88 X 19.53125 mv = 1.71875 \* 28 EX Dusing LM35D in The Range (202 115°C) design s.c cct for (ony v) Voltage Reference ADC: a] what is the digital OIP if The Temp(37°, 107°)
b] what is Temp if The digital OIP is (61010101)? Sensor O/P Range (20X 10 mu ~ 115 x 10 ml) (0.2V~1.15V) Vo = m Vin + offset 6 = m 0.2 + offset 6 4 = m 1.15 + offset @ €)-0 4 = @mo.95 m= 4.21052 offset = -0.8421 Vo = 4.21052 Vi -0.8421€

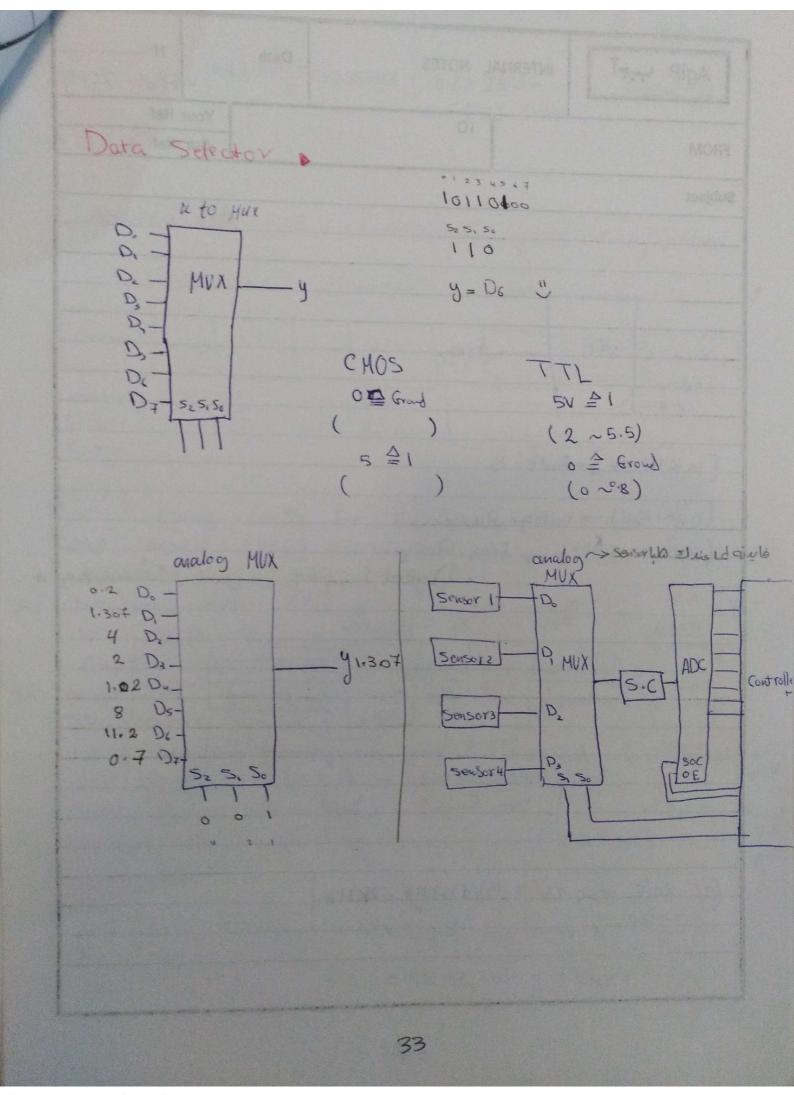


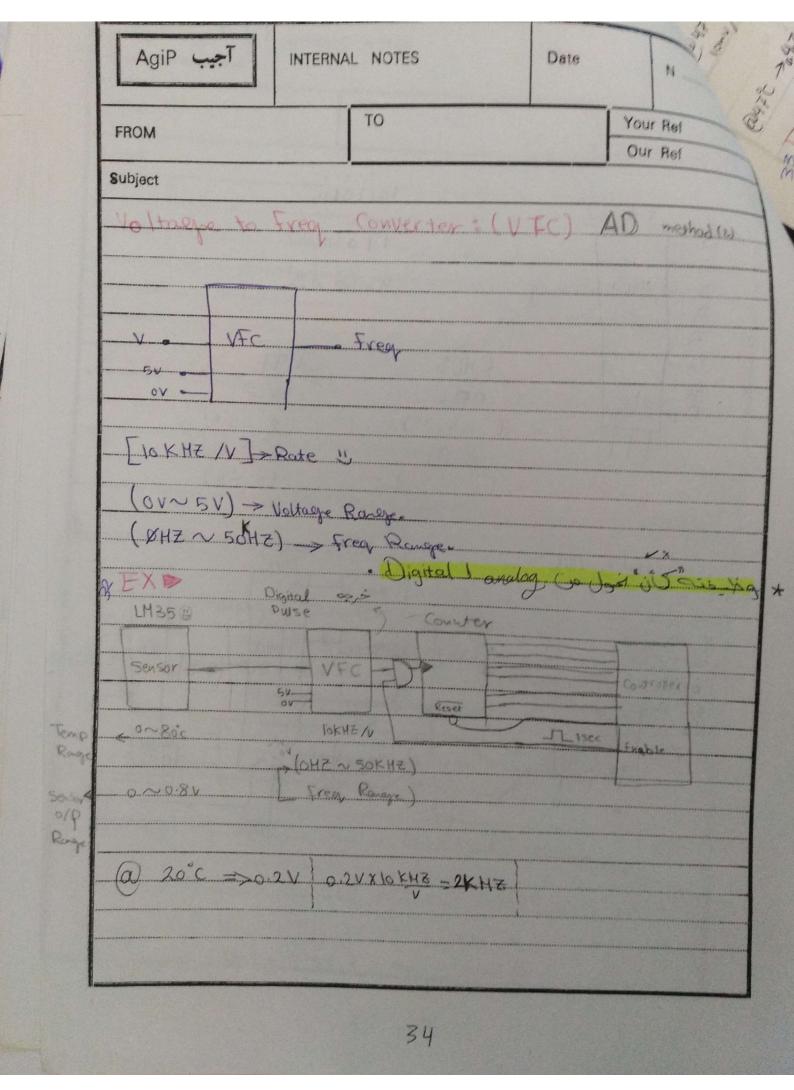
128 64 32 \$6 8 4 21 (0 0 1 0 1 1 0 1)2 \$# @ 107°C Sensor OIP = 1070 X 10 mu = 1.07 V Vo= 4,2105 (1.07)-0.8 WZ1= 3.663135 V D. 0 = 3.663135 = 234,44 ~ 234 128 64 32 16 8 4 2 1 () 1 1 0 1 0 1 0)<sub>2</sub> \* (olololol), = (85), analog I/P = 1.328125 1.328125 - 4.2105 Vi-0.8421 Ui= 0.51543 V 51.540

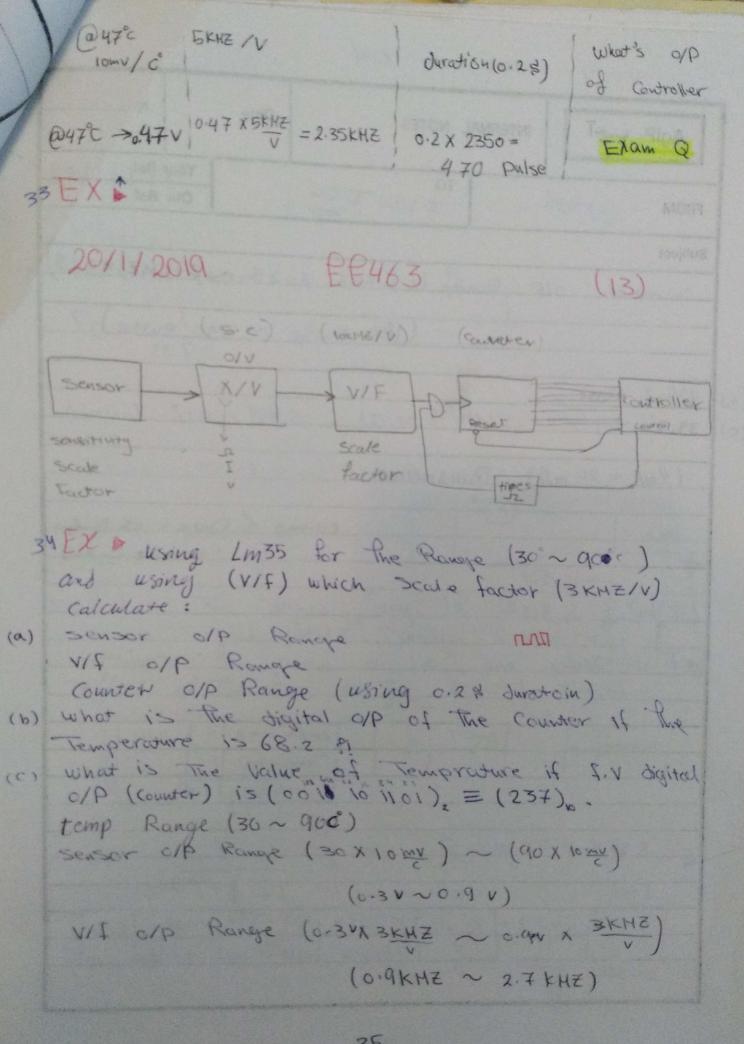


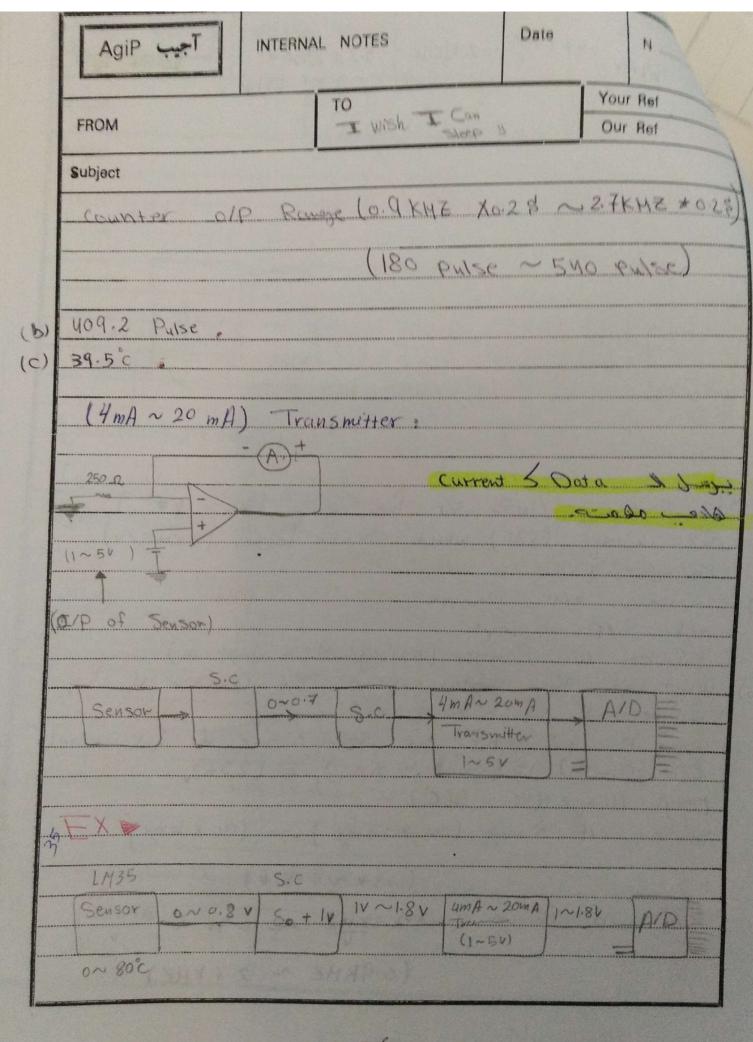




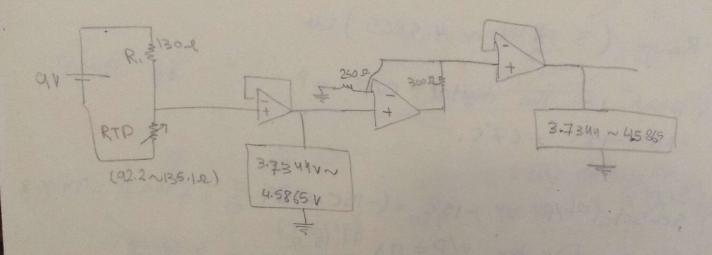








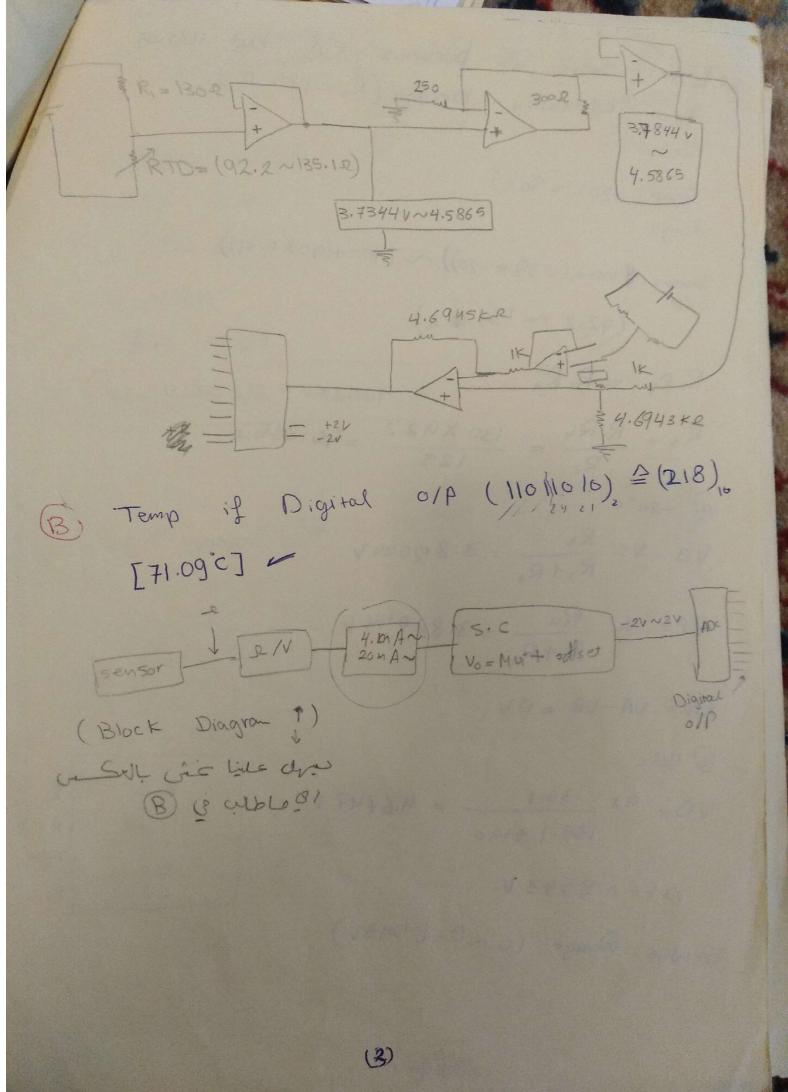
EX: USing RTD PT100 For Temp Range (-20°~90°) in Voltage Devider with R1 = 1300 design Circuit to get The Temperature information for long distance to ADC wich voltage Reference (±2)



Solution: Temp Range (-20°~ 90°) Sensor 0/P [106 + (0:39 x -200)] ~ [100+(0:39 x 96)] (92.22~ 135.1-2)

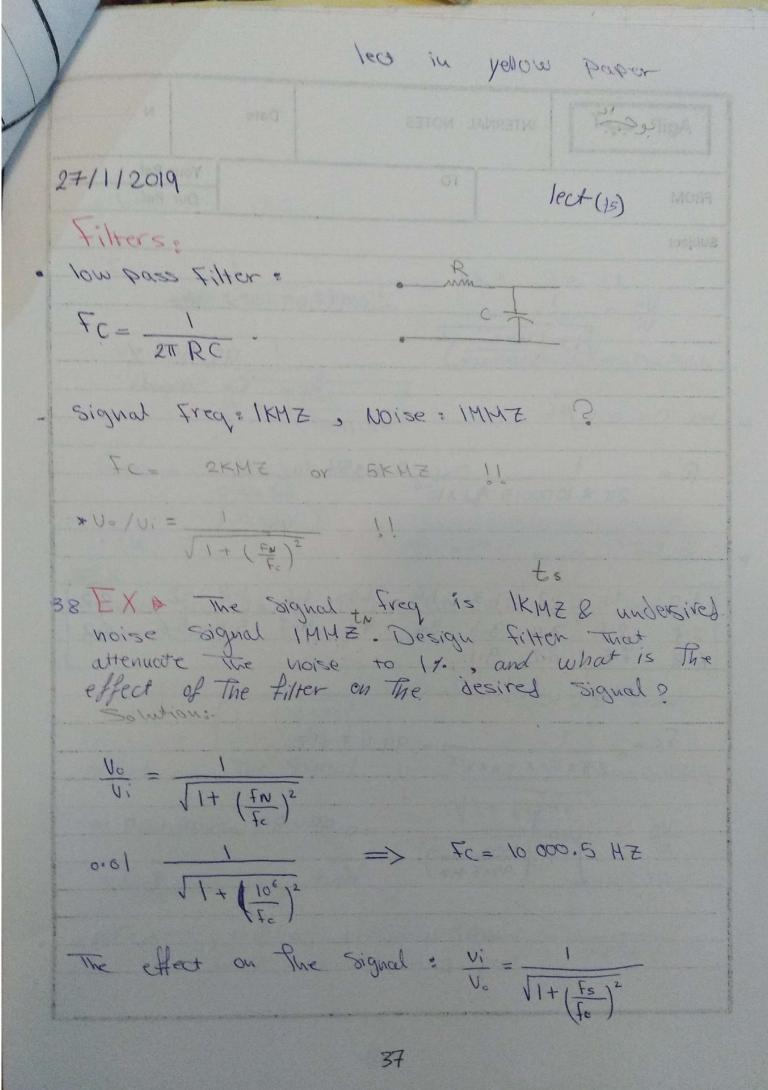
Voltage devider C/P Range  $ort -20^{\circ} \rightarrow Vo = 9 + \frac{92.2}{92.2 + 130} = 3.7544 \text{ Vol}$ at -90°C -> Vo= 0 + 135.1 +130 = 4.5865 Vola

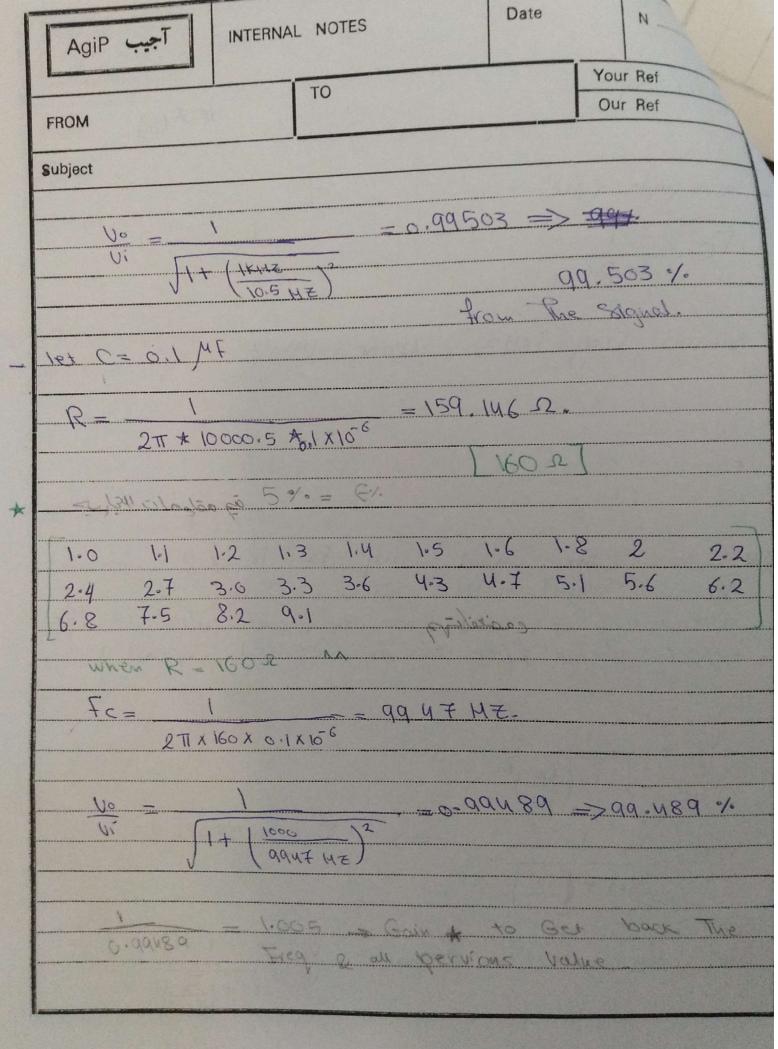
-2=3.7544 M + offset +2=4.5865 M + offsetM= 4.6943 (1)



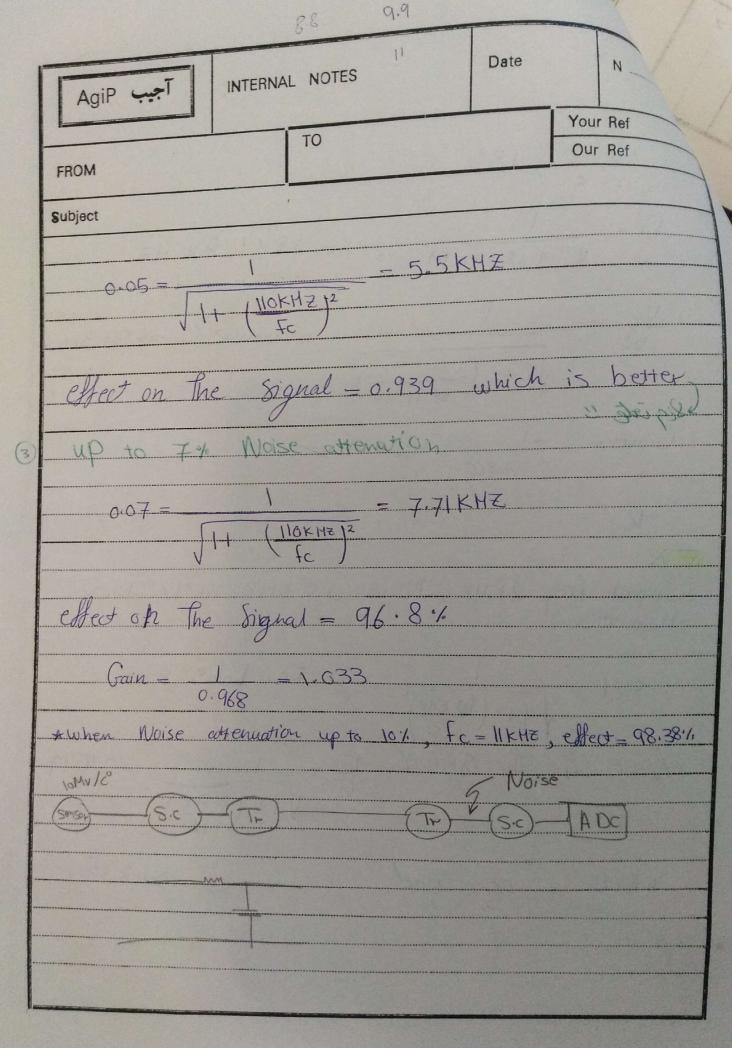
MEX: same as pervious ex but wrigh wheaston bridge (Rz = 125\_0) - Nother Temp (-2000 0900) Ruge Souser (100+(0.39 \* -20))~ (100+(90 × 0.39)) (92.2 ~ 135. Be) RIRY = RERS R3 = R, R4 = 130 X92.2 = 95.888.2 125 (a) -20° c VB = VS R3 = 3.82644V VP= V= Ru = 3.82044 V DV = VA-UB = OV @ 90° c VO= 9x 135.1 R 3 8 - = 4.6747 V AV= 0.8543 V. bridge Range (0~0.85431) (4)

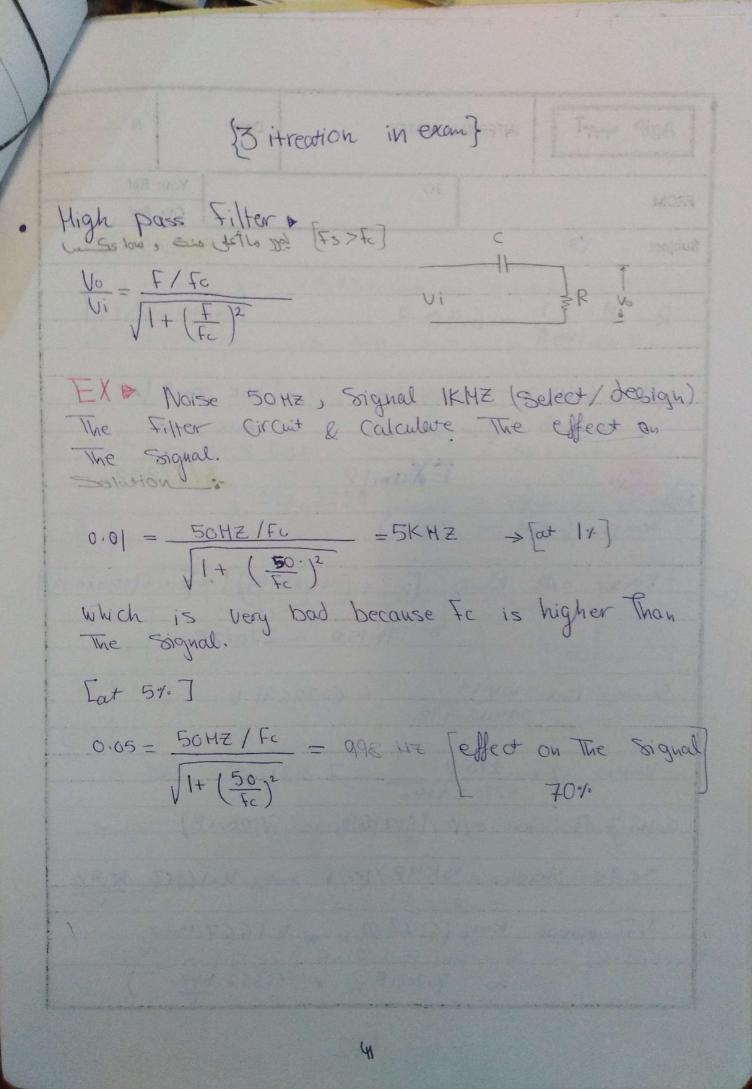
S.C 1~1.8543V 4-20 (mA) S.C ]-2~2V U-UM+after 2=1.8543 M+0HSet -2= 1M+ offset 4 = 0:8543 AM M=4.6821 of set = -6.682 Vo= 4.6821 (V; - 1.42716) 2000 LS Grait de (5)

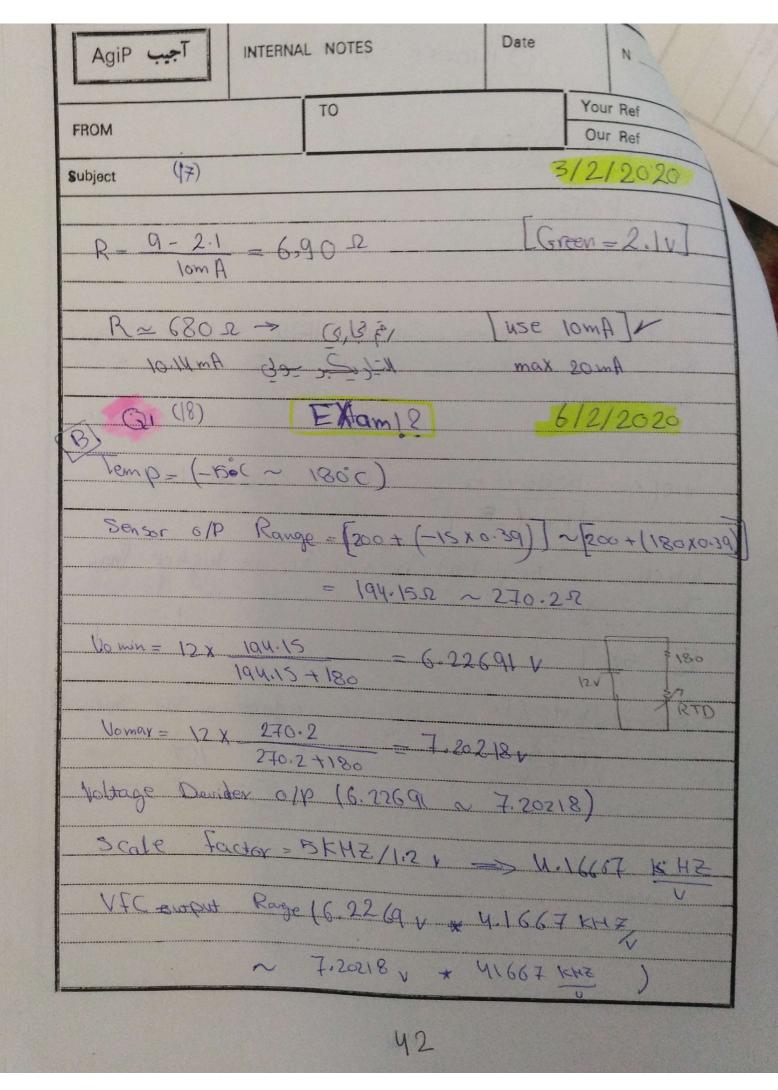


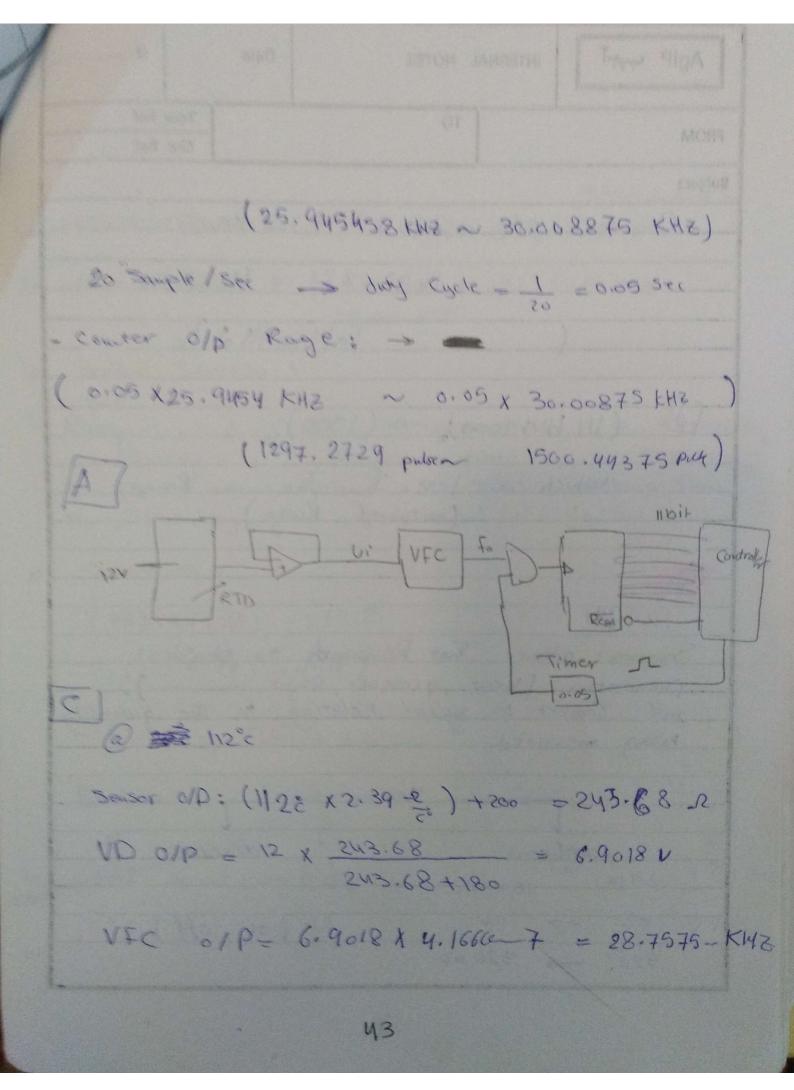


when R = 180 FC= 27 \* 180 \* 0.1 \* 16-6 = 8841. 94 HZ Vi = 1 + (1000 )2 8841.94) = 0.00366 => 90.366% Gain = 1 = 1006 V 30/1/20 20 FE 463 (16) Signal Freq 2KHZ, Noise 110 KHZ of [14 Noise 7-NOitonna Ho 0.0] = T => FC = 1.005 KHZ. effect on the signal. vo = 1 = 0.4819 which is very bad =>48.19 % @ up to 5%. Noise attenuation. 39

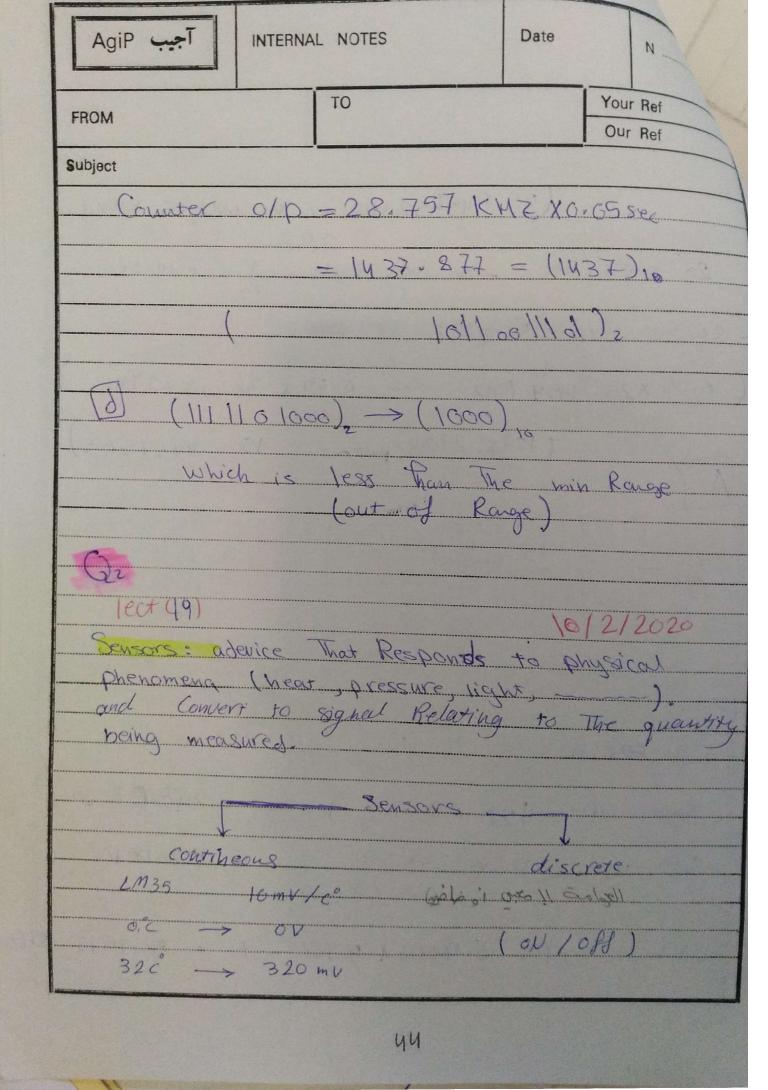




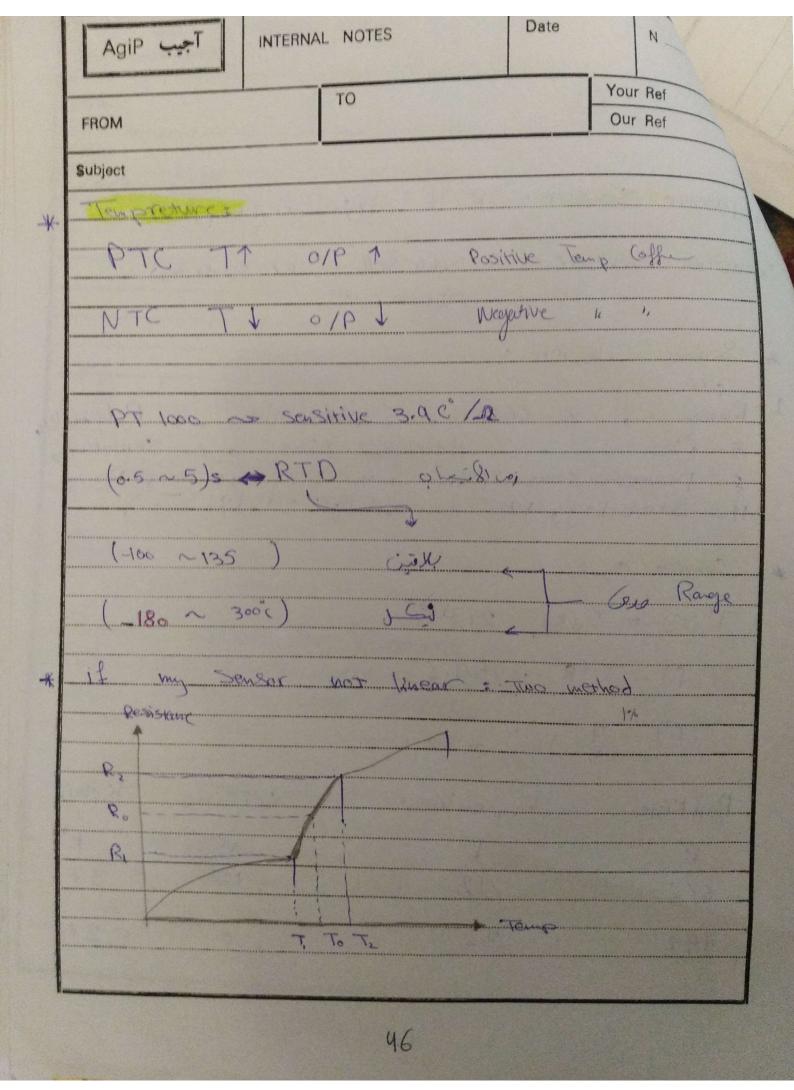




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11	Dies Date	TT HTERNAL NO	
Vous Ref		01	FROM
		A.C.	Zoolons
passive Sen	sor: R, L o		sidealo
active sens	sor: solar sell	ple	
Sensor Sele	ection :		
019		permobilition 11	Reblian
0,,	- ( - 1		
Ross	2- Cost , 3- 8	time 7	Sensitivi
Range,	Response	time , 4-	301101
Range, 5-linearity	, 6- Response	- Size , 10-Ter	mp Rang
Range, 5-linearity	Response	- Size , 10-Ter	mp Rang
Range, 5-linearity	consumption , 9 ty, 12 - avilabili	- Size , 10-Ter	mp Rang
Range, 5- linearity 8- power 11- Stabili- Convert of	consumption , 9 ty, 12 - avilabili	- Size , 10-Ter	mp Rang
Range, 5- linearity 8- power 11- Stabili- Convert of	consumption , 9 ty, 12 - avilabili (K) - 273.15	- Size , 10-Ter	mp Range
Range, 5- linearity 8- power 11- Stabili- Convert of	consumption , 9 ty, 12 - avilabili	- Size , 10-Ter	mp Rang
Range, 5-linearity 8-power 11- Stability Convert of T(f) = T	(k) -459.6	- Size , 10-Ter	mp Rang
Range, 5-linearity 8-power 11- Stability Convert of T(f) = T	6 - Response  consumption , 9  ty, 12 - avilabili $(K) - 273.15$ $(R) - 459.6$ $T(C) + 32$	time , 4 Size , 10-Ter ty: 13-life Tim	mp Rang
Range, 5-linearity 8-power 11- Stability Convert of T(f) = T	(k) -459.6	time , 4-  - Size , 10-Ten  ty: 13-life Tim  Celsius	mp Rang
Range, 5- linearity 8- power 11- Stabili- Convert of T(c) = T T(f) = T T(f) = T	6 - Response  consumption , 9  ty, 12 - avilabili $(K) - 273.15$ $(R) - 459.6$ $T(C) + 32$	celsius	mp Rang
Range, 5- linearity 8- power 11- Stability Convert of T(c') = T T(f') = T Rankine P''	consumption , 9 ty, 12 - avilabili (K) - 273.15 (R) - 459.6 Fahren lieut	time , 4-  - Size , 10-Ten  ty: 13-life Tim  Celsius	mp Rang
Range, 5- linearity 8- power 11- Stability Convert of T(c) = T T(f) = T T(f) = T Rankine	consumption , 9 ty, 12 - avilabili (K) - 273.15 (R) - 459.6 Fahren hient $\Gamma$	celsius	mp Rang



linear approximation method

R(T) = R(To) (1+ 00 AT)

ST = T- To

 $Q_0 = \frac{1}{R(T_0)} \frac{R_2 - R_1}{T_2 - T_1}$ 

R(T) approximation of Resistance at Temp ?

 $R(T_6)$ 

11 11 10

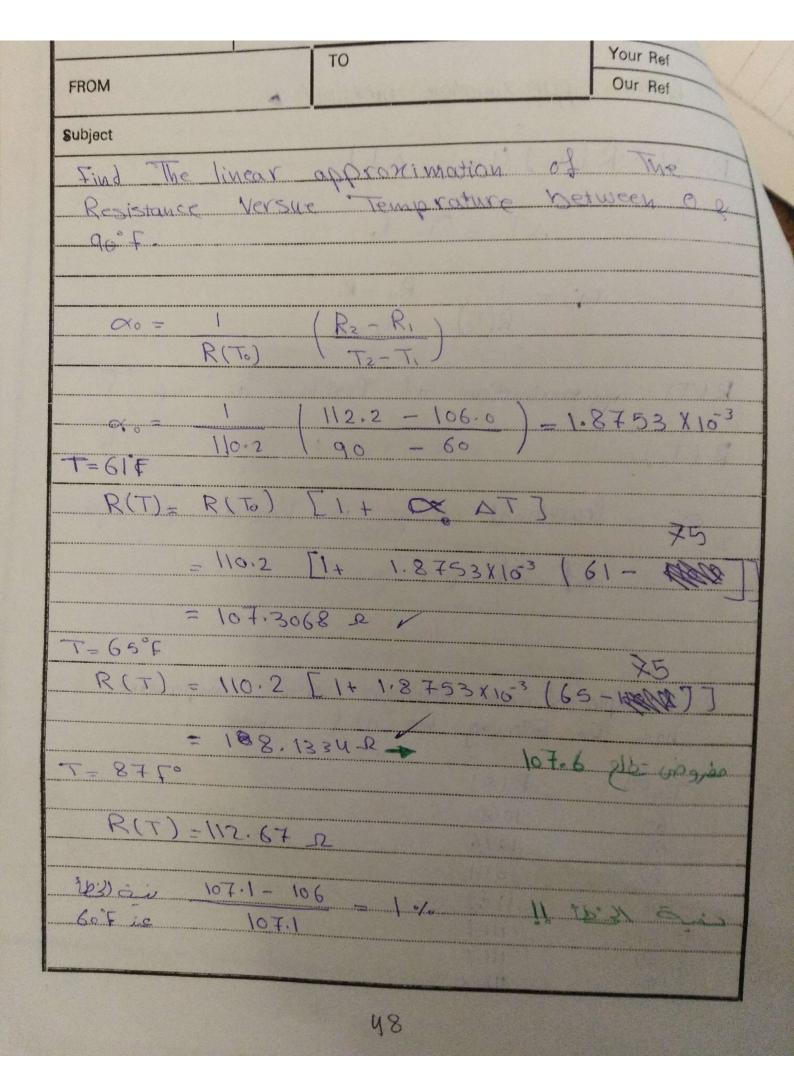
do = fractional charge in Resistance per tegree of Temp.

lec+(20) 13/2/2020

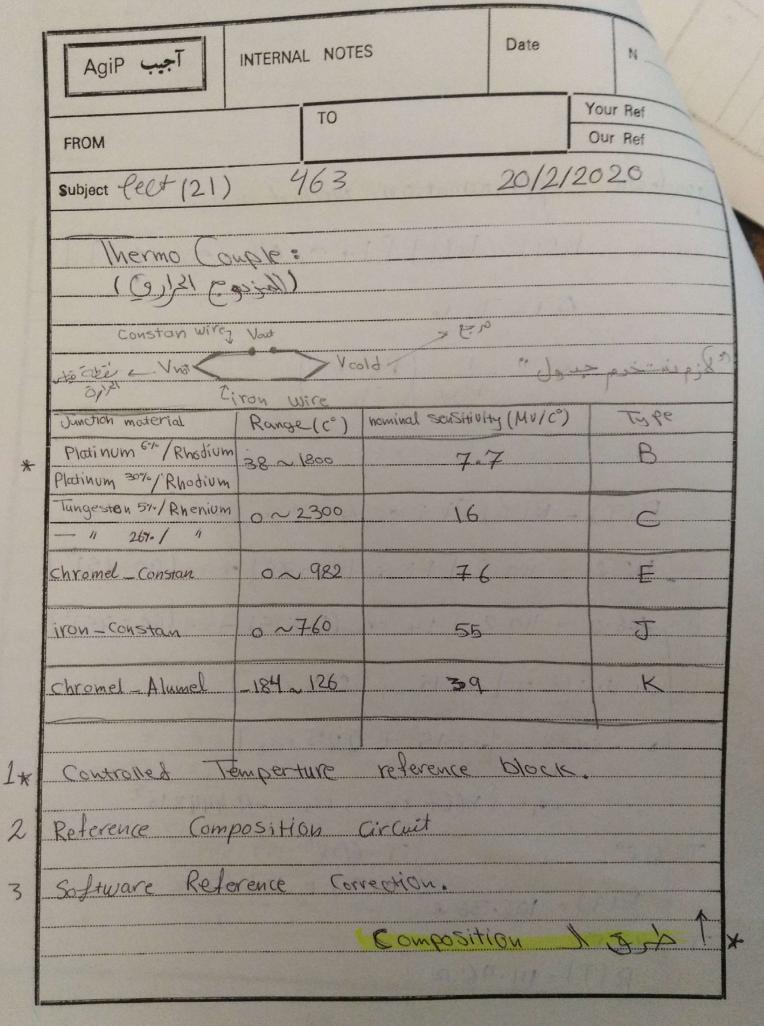
Ex a Sample of metal Resistance Versu Temperature has the following measured values.

T(F°) R(2) 1060 R. 60 1076 65 1091 70 1102 R. 111.1 111.7 112.2 Rz

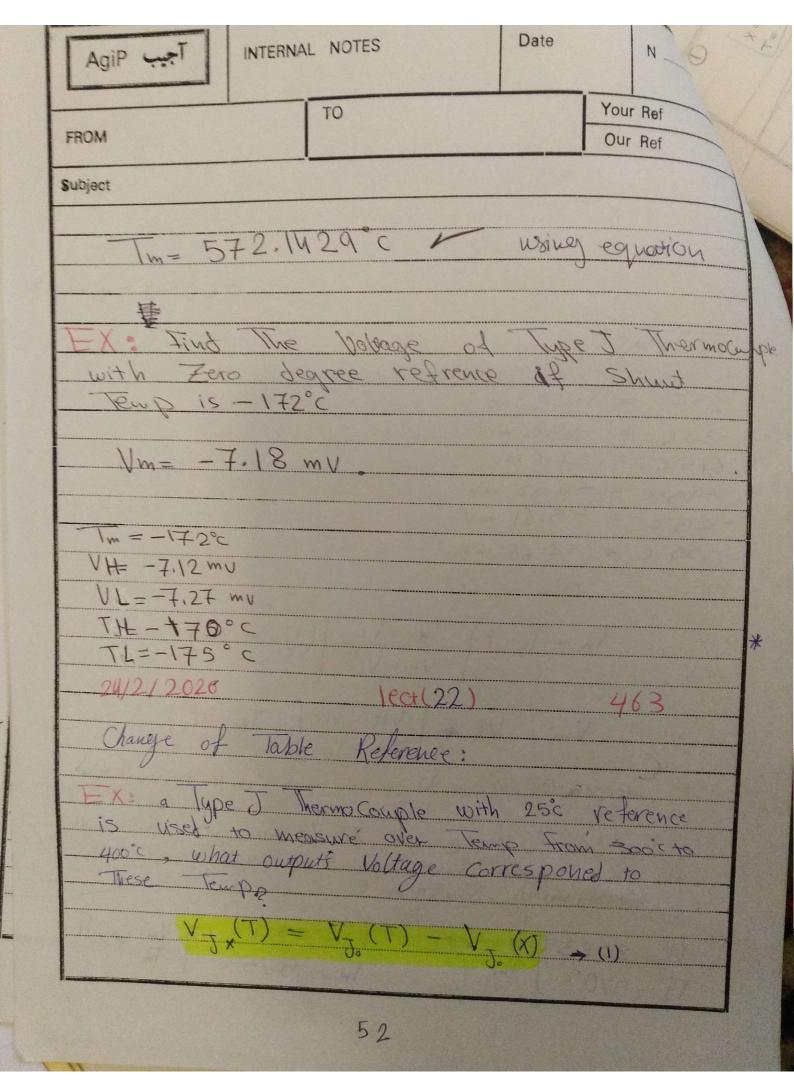
90

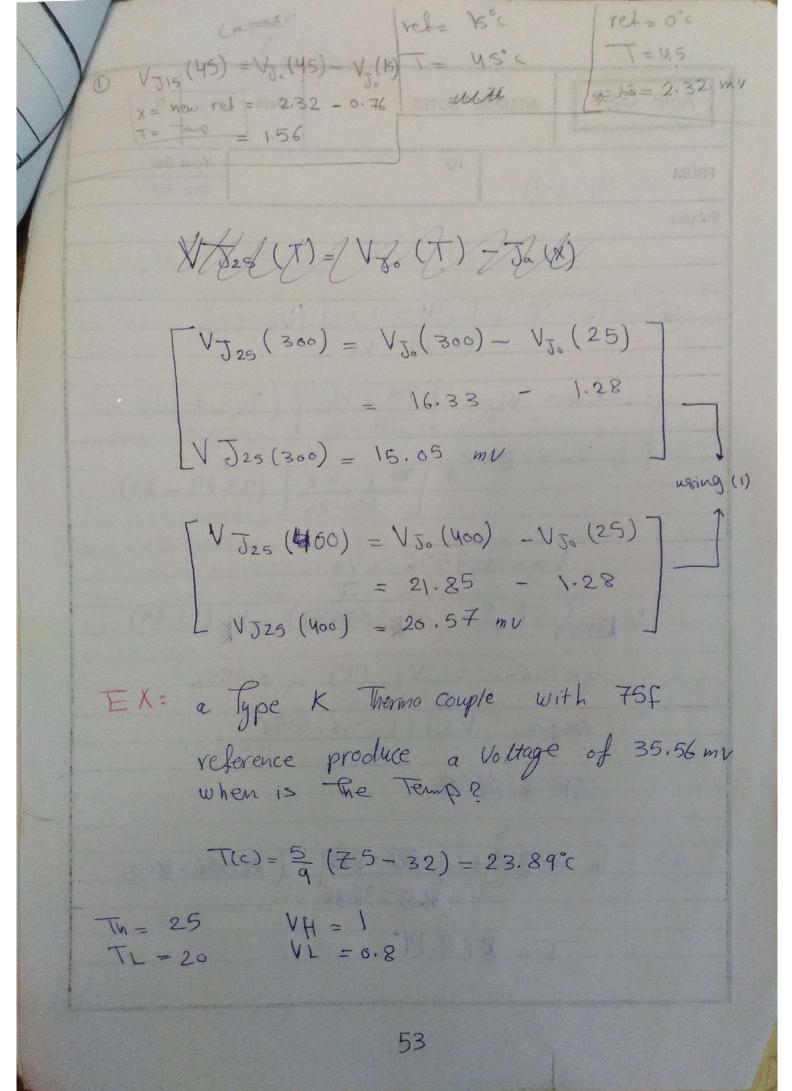


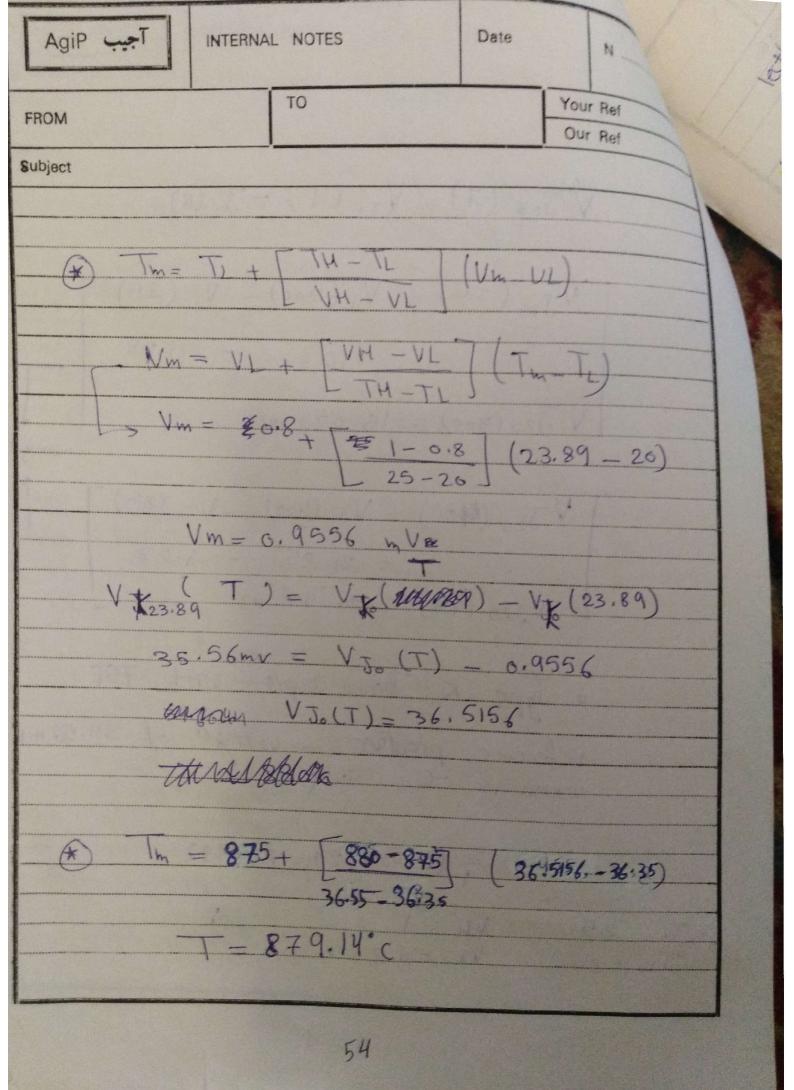
quadratic approximation. method : MANNER R(T) = R(To) [1+0, AT + 02 (AT)] DT = TTO  $\alpha_1 = \frac{1}{R(T_0)} \left( \frac{R_2 - R_1}{T_0 - T_0} \right)$ Same as pervious Ex asing quadratics R(T) = R(To)[1+0, DT +0, (DT)] - 112.2 = 110.2 [1+ x, (90-75) + x2 (90-75)] -106.0 = 110.2 [1+ 01 (60-75) +02 (60-75)2] 0.018 = [ 0, 15 + 225 0, ] La -6:038 = [01/15 + 225 02] a, = 1.8667 x103, 02= -4.444 x 10 T=655° 107.644 ... T= 614° 106.348 R(T) = 107.65 2 R(T) = 106.36 & T = 87 F° 11.7172 R(T)=111.96.2

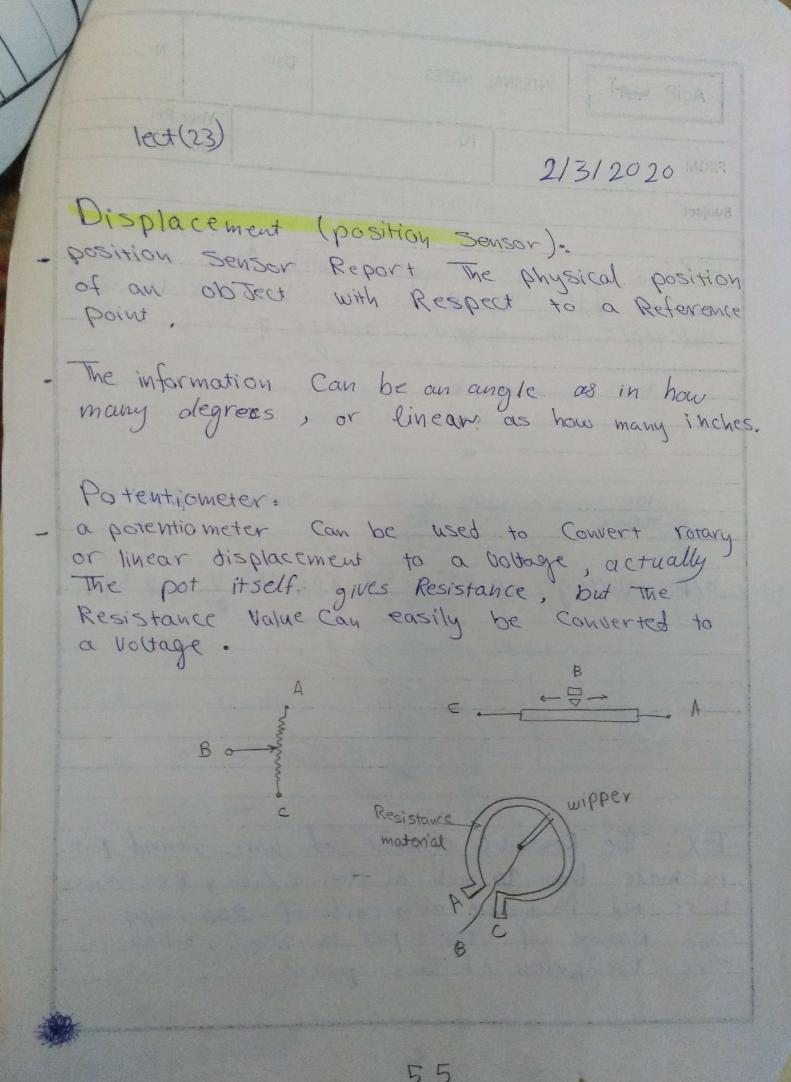


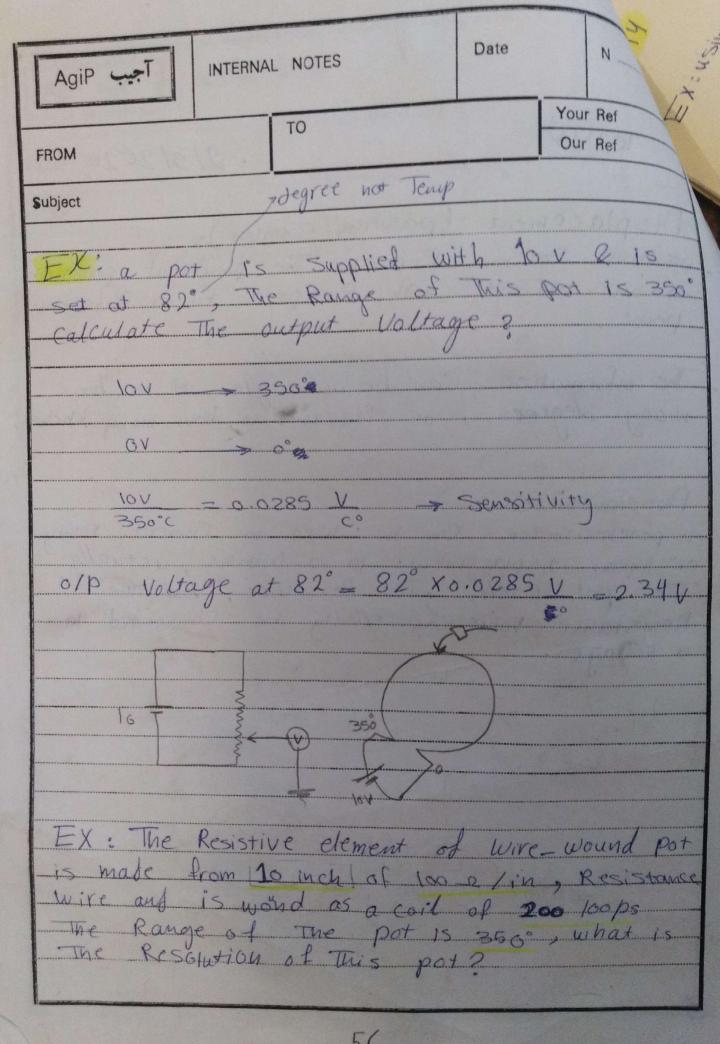
\* is their in MV 10 15 20 -الفوقات ولو بلالب 4-91 1 11 o'c oxypac \* J- Tape 25°C = 1.28 mu -30°C = -1.48 mu 675°C = 37.6 mU -950C = - U.UZ MV -125°c = -5.61 mv -55°C = -2.66 mV Tm=TL+ TH-TL (Vm-VL) Vm = VL + VH - VL (TM-TL) Werpowion do i & i le rel normani EX a Voltage of 23.72 mv is measured with K Thermo Couple, Find The Temperture noteunt tremmens to VH = 23.84 7 Vm is No TH = 575°C Tm VL= 23.63 } Vm is see! TL = 570°C | Tm 51











Resolution -> Telens is any Pot R total = 10 inch x 100 = 1000 :2  $\frac{10002}{2001000} = \frac{52}{1000}$  $-\frac{350^{\circ}}{200100p} = 1.75 \frac{\circ}{100p} \rightarrow Resolution , 50 \frac{1}{200} \text{ for}$ ioimal # Rotary Encoder: 250 > cariagina pyle y IL senom cons # Wichemental Market mental incoder # absolute Incoder +الداوة الداخلية كاتحب، ١١٥٠